
Communications Network Design

lecture 12

Matthew Roughan

<matthew.roughan@adelaide.edu.au>

Discipline of Applied Mathematics
School of Mathematical Sciences
University of Adelaide

March 2, 2009

Budget constraint model and branch and bound

Branch and bound is a standard technique for solving integer programs, by relaxing the problem to the non-integer problem to find bounds, and using these to prune a tree of the possible solutions (rather than evaluating all possible solutions).

Budget Constraint Model

- separable linear cost model

$$\begin{aligned} C(\mathbf{f}) &= \sum_{e \in L(\mathbf{f})} (\beta_e + \alpha_e f_e) \quad \text{where } L(\mathbf{f}) = \{e \in E : f_e > 0\} \\ &= \sum_{e \in L(\mathbf{f})} \beta_e + \sum_{\mu \in P} l_\mu(L(\mathbf{f})) x_\mu \end{aligned}$$

- separate costs into

- initial **investment** costs (of laying optical fibre)

$$C_{\text{inv}}(L) = \sum_{e \in L} \beta_e$$

- **operations** cost of lighting up the link

$$C_{\text{op}}(\mathbf{f}, L) = \sum_{e \in L} \alpha_e f_e$$

Budget Constraint Model (BCM)

- earlier, we considered the problem

$$\min C(\mathbf{f}) = \min [C_{\text{inv}}(L) + C_{\text{op}}(\mathbf{f}, L)]$$

subject to the appropriate constraints

- budget constraint model
 - have a budget constraint on the investment costs

$$C_{\text{inv}}(L) \leq B$$

- consider the optimization problem

$$\min C_{\text{op}}(\mathbf{f}, L) \text{ subject to } C_{\text{inv}}(L) \leq B$$

with additional constraints as above.

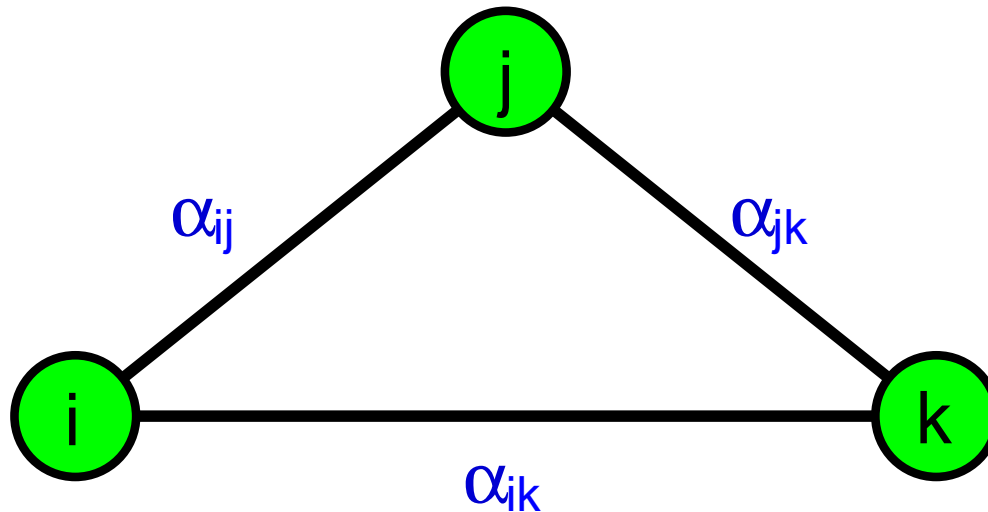
Formulation: of BCM

$$\begin{aligned} (P') \quad & \min \quad C(\mathbf{f}) = \sum_{e \in L} \alpha_e f_e \\ & \text{s.t.} \quad f_e = \sum_{\mu: e \in \mu} x_\mu \quad \forall e \in E \\ & \quad \quad \sum_{\mu: \mu \in P_k} x_\mu = t_k \quad \forall k \in K \\ & \quad \quad \sum_{e \in E} \beta_e z_e \leq B \\ & \quad \quad x_\mu \geq 0 \quad \forall \mu \in P \\ & \quad \quad z_e = 0, \text{ or } 1 \quad \forall e \in E \end{aligned}$$

$$z_e = \begin{cases} 1 & \text{if link } e \in L \text{ (i.e. we use } e\text{)} \\ 0 & \text{if link } e \notin L \text{ (i.e. we don't use } e\text{)} \end{cases}$$

BCM and the triangle inequality

- α_e satisfy the triangle inequality



$$\alpha_{ij} < \alpha_{ik} + \alpha_{kj}$$

- because β_e have been moved into constraints
- otherwise, link $e = (i, j)$ could be deleted as it is a longer path than $i-k-j$

BCM and Branch and Bound

- this is an old, well studied problem, e.g. see [1]
- NP-hard
- look for heuristic solutions
 - branch and bound [2]
- **Branch and Bound** is the topic of this lecture.

Notation

We can write an optimization problem several different ways

- integer linear programming problem, called (IP)

$$(IP) \left\{ \begin{array}{ll} \text{maximize} & \mathbf{c}^T \mathbf{x} \\ \text{subject to} & A\mathbf{x} \leq \mathbf{b} \\ & \mathbf{x} \geq \mathbf{0} \\ & \mathbf{x} \in \mathbb{Z}^n \end{array} \right.$$

- short form

$$\max\{\mathbf{c}^T \mathbf{x} \mid A\mathbf{x} \leq \mathbf{b}, \mathbf{x} \geq \mathbf{0}, \mathbf{x} \in \mathbb{Z}^n\}$$

Integer programming

- Take an integer linear programming problem

$$\max\{\mathbf{c}^T \mathbf{x} \mid A\mathbf{x} \leq \mathbf{b}, \mathbf{x} \geq 0, \mathbf{x} \in \mathbb{Z}^n\}$$

- some of our variables are real (e.g. link loads)
 - we have a **mixed**-integer linear programming problem
- \mathbb{Z}^n is the set of n -dimensional vectors of integers
 - we will restrict to $\mathbf{x} \in \{0, 1\}^n$
- Many other classic examples
 - travelling salesman problem
 - knapsack problem
 - set covering problem
 - machine scheduling problem

Converting BCM into integer program

Variables are

$$z_e = \begin{cases} 1 & \text{if link } e \in L \text{ (i.e. we use } e\text{)} \\ 0 & \text{if link } e \notin L \text{ (i.e. we don't use } e\text{)} \end{cases}$$

Write optimization objective

$$C(\mathbf{f}) = \sum_e \alpha_e f_e \quad (1)$$

$$= \sum_e \alpha_e \sum_{\mu: e \in \mu} x_\mu \quad (2)$$

$$= \sum_e \sum_{\mu} \alpha_e A(e, \mu) x_\mu \quad (3)$$

$$= [\alpha^t A] \mathbf{x} \quad (4)$$

Converting BCM into integer program

We derive the routing vector \mathbf{x} from the \mathbf{z} by solving the shortest path problem (with linear costs) on the graph determined by the \mathbf{z} .

Converting BCM into integer program

Obvious constraints given in the BCM are

$$\sum_{\mu: \mu \in P_k} x_\mu = t_k, \quad \forall k \in K \quad (5)$$

$$\sum_{e \in E} \beta_e z_e \leq B \quad (6)$$

we just need to write these in matrix form, but there is a less obvious constraint

$$(1 - z_e) f_e = (1 - z_e) \sum_{\mu: e \in \mu} x_\mu = 0 \quad (7)$$

which says we cannot put traffic on absent links.

Relationship to linear programming

For each integer program:

$$(IP) \quad \max\{\mathbf{c}^T \mathbf{x} \mid A\mathbf{x} \leq \mathbf{b}, \mathbf{x} \geq 0, \mathbf{x} \in \mathbb{Z}^n\}$$

there is an associated linear program:

$$(LP) \quad \max\{\mathbf{c}^T \mathbf{x} \mid A\mathbf{x} \leq \mathbf{b}, \mathbf{x} \geq 0\}$$

Now (LP) is less constrained than (IP) so

- If (LP) is infeasible, then so is (IP)
- If (LP) is optimized by integer variables, then that solution is feasible and optimal for (IP)
- The optimal objective value for (LP) is greater than or equal to the optimal objective for (IP)

Bounds

- call the (LP) a **relaxation**
 - because we have relaxed some constraints
- it is easy to solve (usually)
 - its a standard linear program
 - can use simplex, or interior point methods
- rounding off the solution to the relaxation might work badly
 - it could even produce a partitioned graph
 - not all traffic can get through!
- but the (LP) relaxation does provide a **bound**
 - we can use this to **prune branches**

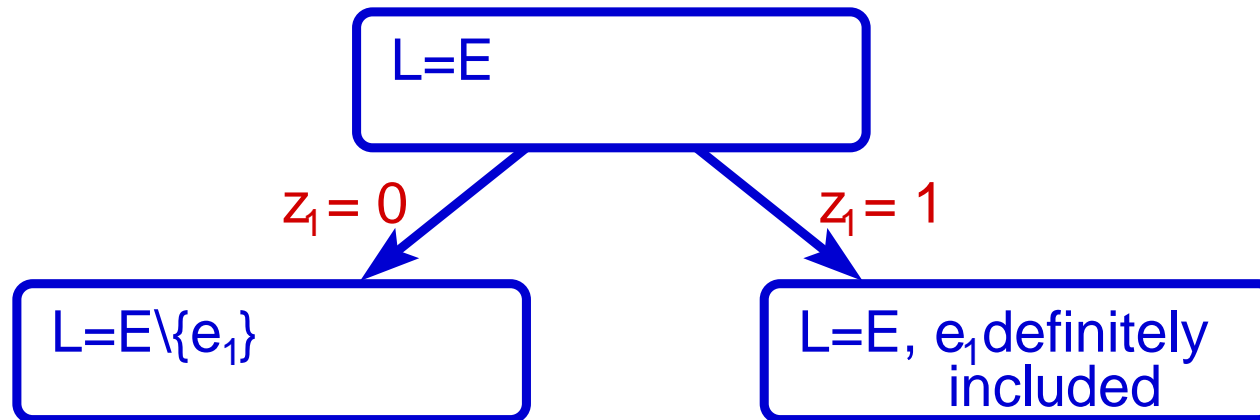
Branching

- the above gives us bounds for solutions
- we also need to branch
 - at each point where we don't have an integer solution, we can branch by splitting the possible solutions into two partitions
 - for example, we require $x_1 \in \{0, 1\}$, but the relaxation solution was $x_1 = 0.2$, we then subdivide the problem into two parts
 - $x_1 = 0$
 - $x_1 = 1$
 - then solve each of these subproblems

Branching example

For the network problem, we have decision variables

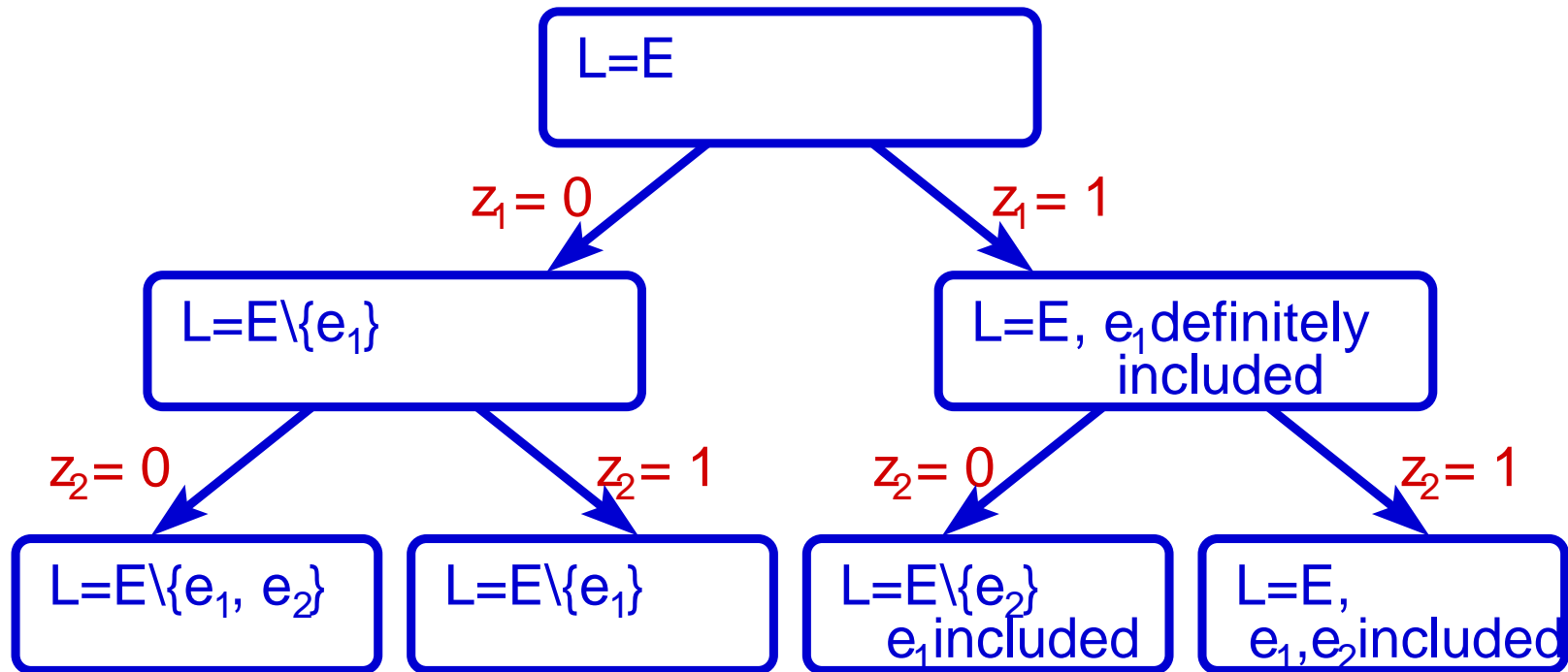
$$z_e = \begin{cases} 1 & \text{if link } e \in L \text{ (i.e. we use } e\text{)} \\ 0 & \text{if link } e \notin L \text{ (i.e. we don't use } e\text{)} \end{cases}$$



Branching example

For the network problem, we have decision variables

$$z_e = \begin{cases} 1 & \text{if link } e \in L \text{ (i.e. we use } e\text{)} \\ 0 & \text{if link } e \notin L \text{ (i.e. we don't use } e\text{)} \end{cases}$$



Branch and Bound

- **key:** if upper bound of a subproblem is less than objective for a known integer feasible solution, then
 - the subproblem cannot have a solution greater than the already known solution
 - we can eliminate this solution
 - we can also prune all of the tree below the solution
- it lets us do a **non-exhaustive** search of the subproblems
 - if we get to the end, we have a proof of optimality without exhaustive search

Branch and Bound: algorithm

1. **Initialization:** initialize variables, in particular, start a list of subproblems, initialized with our original integer program.
2. **Termination:** terminate the program when we reach the optimum (i.e. the list of subproblems is empty).
3. **Problem selection and relaxation:** select the next problem from the list of possible subproblems, and solve a relaxation on it.
4. **Fathoming and pruning:** eliminate branches of the tree once we prove they cannot contain an optimal solution.
5. **Branching:** partition the current problem into subproblems, and add these to our list.

Branch and Bound: example

Consider the problem (from [2])

$$\text{IP}^0 \left\{ \begin{array}{ll} \text{maximize} & 13x_1 + 8x_2 \\ \text{subject to} & x_1 + 2x_2 \leq 10 \\ & 5x_1 + 2x_2 \leq 20 \\ & x_1 \geq 0, x_2 \geq 0 \\ & x_1, x_2 \text{ integer} \end{array} \right.$$

Branch and Bound: algorithm

Initialization:

- initialize the list of problems \mathcal{L}
 - set initially $\mathcal{L} = \{\text{IP}^0\}$, where IP^0 is the initial problem
 - often store/picture \mathcal{L} as a tree
- incumbent objective value $z_{ip} = -\infty$
- initial value of upper bound on problem is $\bar{z}_0 = \infty$
- constraint set of problem IP^0 is set to be
$$S^0 = \{\mathbf{x} \in \mathbb{Z}^n \mid A\mathbf{x} \leq \mathbf{b}, \mathbf{x} \geq 0\}$$

Branch and Bound: algorithm

Termination:

- If $\mathcal{L} = \emptyset$ then we stop
 - If $z_{ip} = -\infty$ then the integer program is infeasible.
 - Otherwise, the subproblem IP^i which yielded the current value of z_{ip} is optimal gives the optimal solution \mathbf{x}^*

Branch and Bound: algorithm

Problem selection:

- select a problem from \mathcal{L}
 - there are multiple ways to decide which problem to choose from the list
 - the method used can have a big impact on speed
 - once selected, delete the problem from the list

Relaxation:

- solve a relaxation of the problem
 - denote the optimal solution by \mathbf{x}^{iR}
 - denote the optimal objective value by z_i^R
 - $z_i^R = -\infty$ if no feasible solutions exist

Branch and Bound: algorithm

Fathoming :

- we say branch of the tree is **fathomed** if
 - infeasible
 - feasible solution, and $z_i^R \leq z_{ip}$
 - integral feasible solution
 - set $z_{ip} \leftarrow \max\{z_{ip}, z_i^R\}$

Pruning:

- in any of the cases above, we need not investigate any more subproblems of the current problem
 - subproblems have more constraints
 - their z must lie under the upper bound
- Prune any subtrees with $z_j^R \leq z_{ip}$
- If we pruned **Goto step 2**

Branch and Bound: algorithm

Branching:

- also called partitioning
- want to partition the current problem into subproblems
 - there are several ways to perform partitioning
- If S^i is the current constraint set, then we need a disjoint partition $\{S^{ij}\}_{j=1}^k$ of this set
 - we add problems $\{IP^{ij}\}_{j=1}^k$ to \mathcal{L}
 - IP^{ij} is just IP^i with its feasible region restricted to S^{ij}
- **Goto step 2**

Branch and Bound: algorithm

1. **Initialization:** initialize variables, in particular, start a list of subproblems, initialized with our original integer program.
2. **Termination:** terminate the program when we reach the optimum (i.e. the list of subproblems is empty).
3. **Problem selection and relaxation:** select the next problem from the list of possible subproblems, and solve a relaxation on it.
4. **Fathoming and pruning:** eliminate branches of the tree once we prove they cannot contain an optimal solution.
5. **Branching:** partition the current problem into subproblems, and add these to our list.

Branch and Bound: example

Consider the problem (from [2])

$$\text{IP}^0 \left\{ \begin{array}{ll} \text{maximize} & 13x_1 + 8x_2 \\ \text{subject to} & x_1 + 2x_2 \leq 10 \\ & 5x_1 + 2x_2 \leq 20 \\ & x_1 \geq 0, x_2 \geq 0 \\ & x_1, x_2 \text{ integer} \end{array} \right.$$

with relaxation

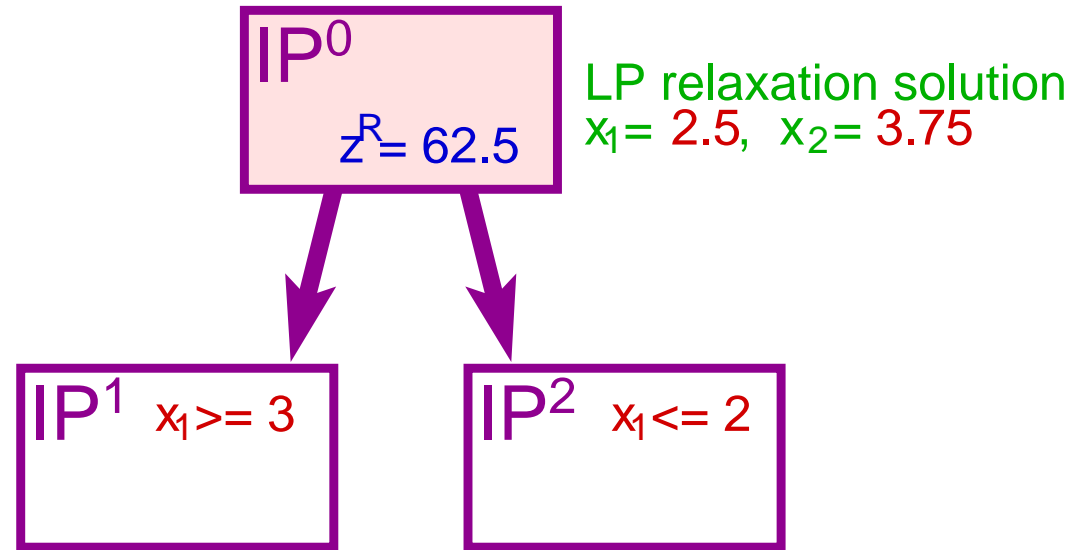
$$\text{LP}^0 \left\{ \begin{array}{ll} \text{maximize} & z = 13x_1 + 8x_2 \\ \text{subject to} & x_1 + 2x_2 \leq 10 \\ & 5x_1 + 2x_2 \leq 20 \\ & x_1 \geq 0, x_2 \geq 0 \end{array} \right.$$

which has solutions $x_1^0 = 2.5$ and $x_2^0 = 3.75$ with $z_0^R = 62.5$

Branch and Bound: example

- we will partition on x_1
 - this is the “most infeasible”
 - furthest from an integral value
- we will partition on x_1
 - partition into two subproblems by adding an extra constraint
 - IP^1 has $x_1 \geq 3$
 - IP^2 has $x_1 \leq 2$
- $\mathcal{L} = \{IP^1, IP^2\}$

Branch and Bound: example



$$\mathcal{L} = \{IP^1, IP^2\}$$

Branch and Bound: example

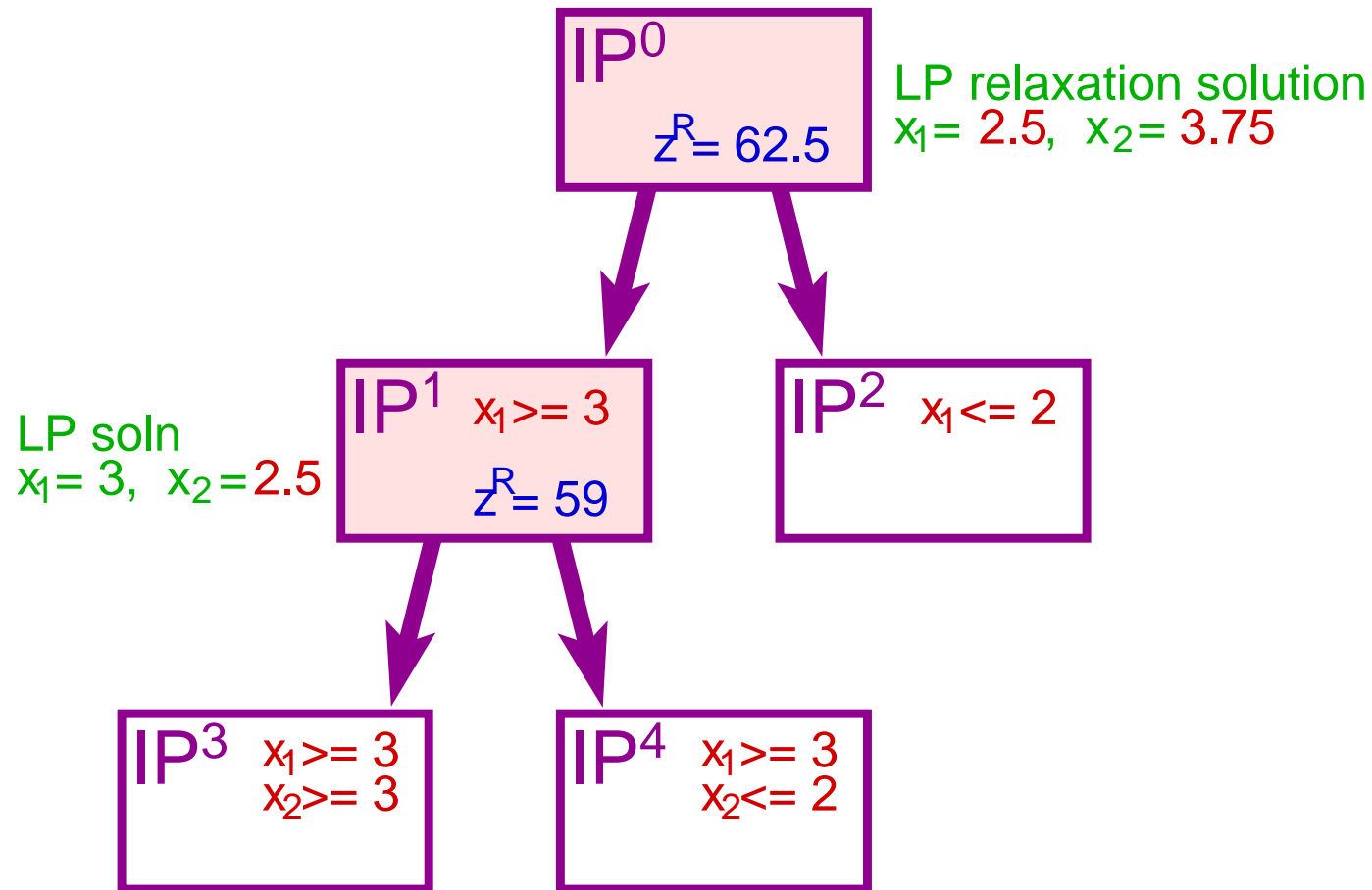
Problem selection (just chose in order) of IP^1

$$IP^1 \left\{ \begin{array}{ll} \text{maximize} & 13x_1 + 8x_2 \\ \text{subject to} & x_1 + 2x_2 \leq 10 \\ & 5x_1 + 2x_2 \leq 20 \\ & x_1 \geq 3 \\ & x_1 \geq 0, x_2 \geq 0 \\ & x_1, x_2 \text{ integer} \end{array} \right.$$

The relaxation (to a LP) has solutions

- $x_1^1 = 3$ and $x_2^1 = 2.5$ with $z_1^R = 59$
- we will next partition on x_2
 - IP^3 has $x_2 \leq 2$
 - IP^4 has $x_2 \geq 3$

Branch and Bound: example



$$\mathcal{L} = \{IP^2, IP^3, IP^4\}$$

Branch and Bound: example

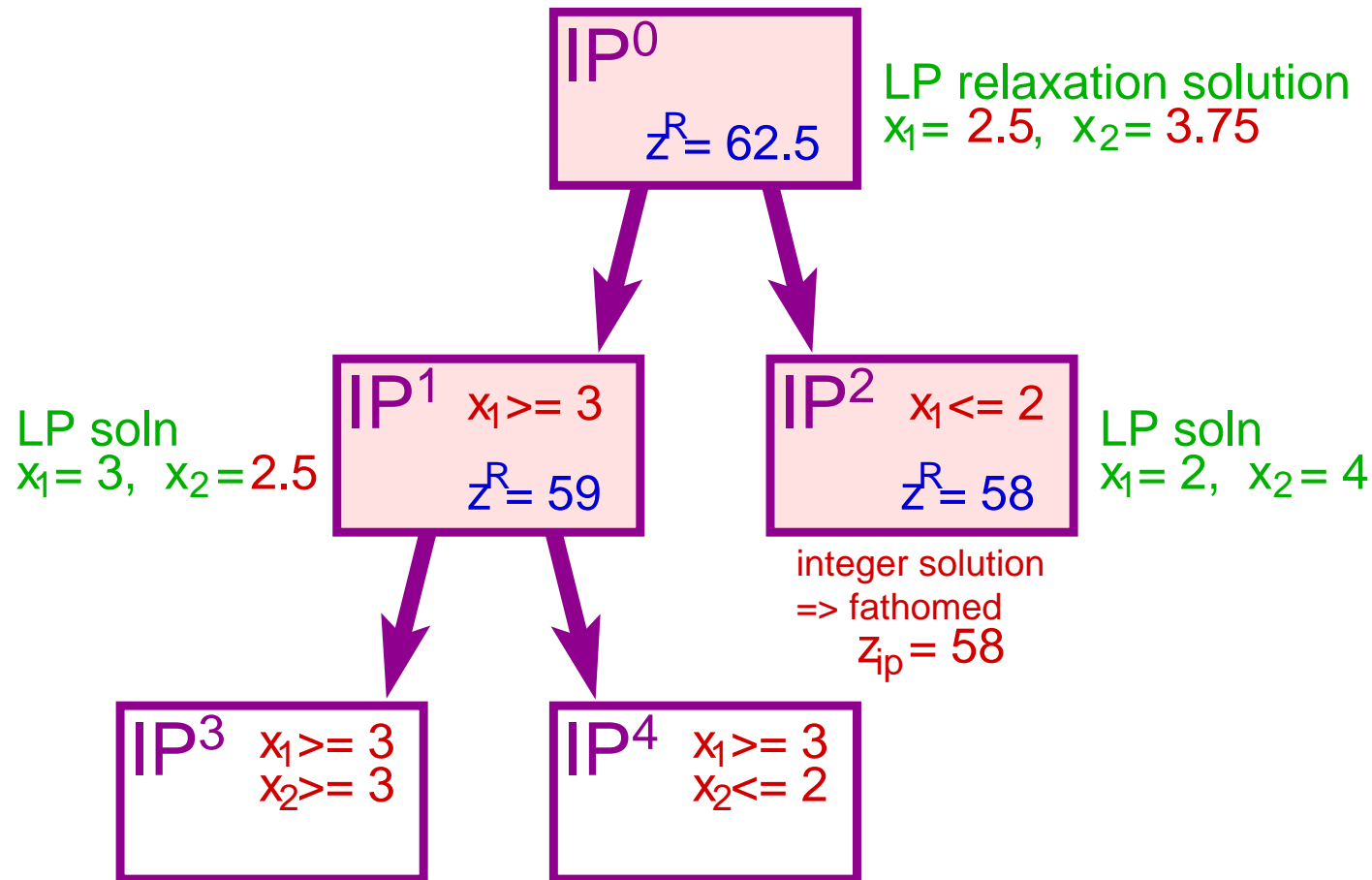
Problem selection (best bound) of IP^2

$$IP^2 \left\{ \begin{array}{ll} \text{maximize} & 13x_1 + 8x_2 \\ \text{subject to} & x_1 + 2x_2 \leq 10 \\ & 5x_1 + 2x_2 \leq 20 \\ & x_1 \leq 2 \\ & x_1 \geq 0, x_2 \geq 0 \\ & x_1, x_2 \text{ integer} \end{array} \right.$$

The relaxation (to a LP) has solutions

- $x_1^2 = 2$ and $x_2^2 = 4$ with $z_2^R = 58$
- integral feasible
- $z_{ip} = 58$
- IP^2 is fathomed

Branch and Bound: example



$$\mathcal{L} = \{IP^3, IP^4\}$$

Branch and Bound: example

Problem selection (order) of IP^3

$$\begin{array}{l} IP^3 \left\{ \begin{array}{ll} \text{maximize} & 13x_1 + 8x_2 \\ \text{subject to} & x_1 + 2x_2 \leq 10 \\ & 5x_1 + 2x_2 \leq 20 \\ & x_1 \geq 3 \\ & x_2 \geq 3 \\ & x_1 \geq 0, x_2 \geq 0 \\ & x_1, x_2 \text{ integer} \end{array} \right. \end{array}$$

The relaxation (to a LP) is infeasible

- $z_3^R = -\infty$
- IP^3 is fathomed
- $\mathcal{L} = \{IP^4\}$

Branch and Bound: example

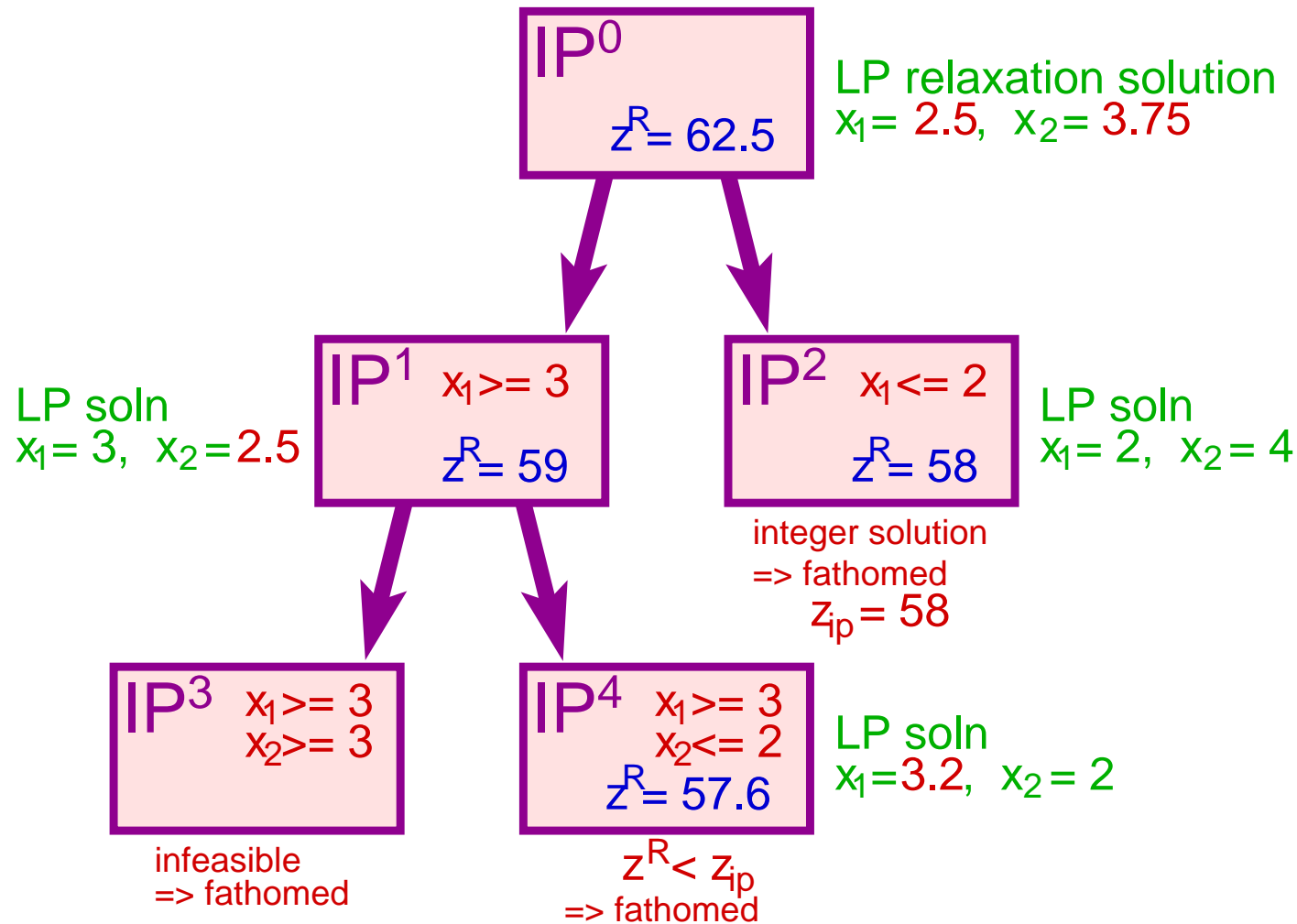
Problem selection (only possible one) of IP^4

$$\begin{array}{l} IP^4 \left\{ \begin{array}{ll} \text{maximize} & 13x_1 + 8x_2 \\ \text{subject to} & x_1 + 2x_2 \leq 10 \\ & 5x_1 + 2x_2 \leq 20 \\ & x_1 \geq 3 \\ & x_2 \leq 2 \\ & x_1 \geq 0, x_2 \geq 0 \\ & x_1, x_2 \text{ integer} \end{array} \right. \end{array}$$

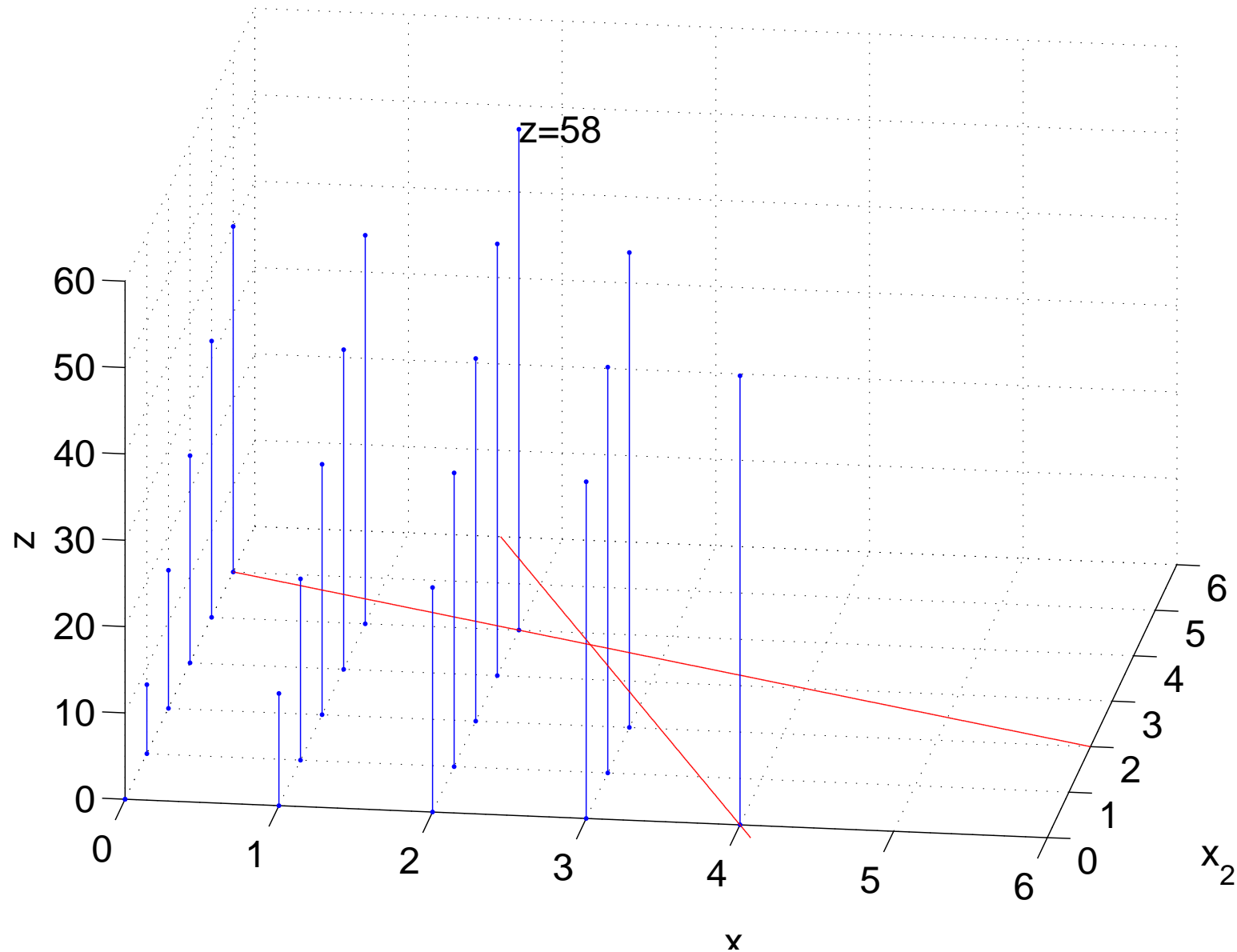
The relaxation (to a LP) has solution

- $x_1^2 = 3.2$ and $x_2^2 = 2$ with $z_4^R = 57.6 < z_{ip}$
- IP^4 is fathomed

Branch and Bound: example



Branch and Bound: example



Branch and Bound

- B&B is a very general algorithm
 - as described above we seek the optimum
 - can also be used as a heuristic
- different strategies available for each step above
 - can use heuristics inside B&B
 - pre-processing of the problem can be good
- no single strategy stands out as best for all problems
 - but sometimes we can exploit properties of a particular problem to do better

References

- [1] D. S. Johnson, J. K. Lenstra, and A. H. G. R. Kan, "The complexity of the network design problem," *Networks*, vol. 8, pp. 279-285, 1978.
- [2] E. K. Lee and J. Mitchell, *Encyclopedia of Optimization*, ch. Branch-and-bound methods for integer programming. Kluwer Academic Publishers, 2001.
<http://www.rpi.edu/~mitchj/papers/leejem.html>.