

Complex-Network Modelling and Inference

Lecture 15: Modelling with Graphs, and Artificial Neural Networks

Matthew Roughan

`<matthew.roughan@adelaide.edu.au>`

https://roughan.info/notes/Network_Modelling/

School of Mathematical Sciences,
University of Adelaide

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Section 1

Modelling

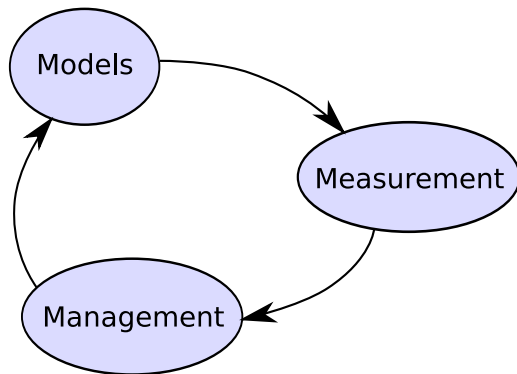
Modelling



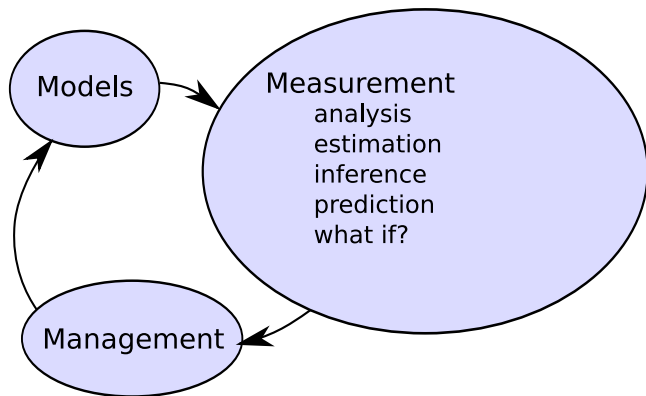
Actually...

Actually I mean Mathematical Modelling

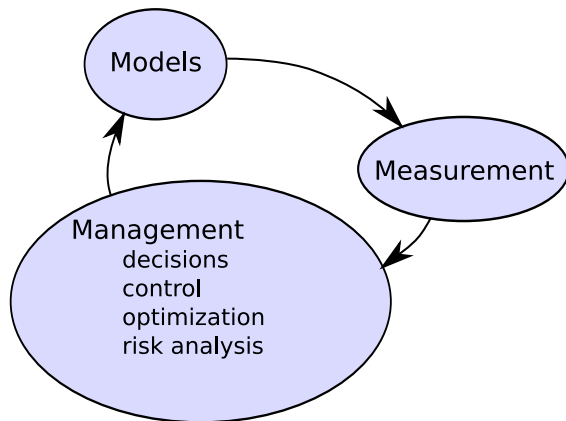
Purpose of our work



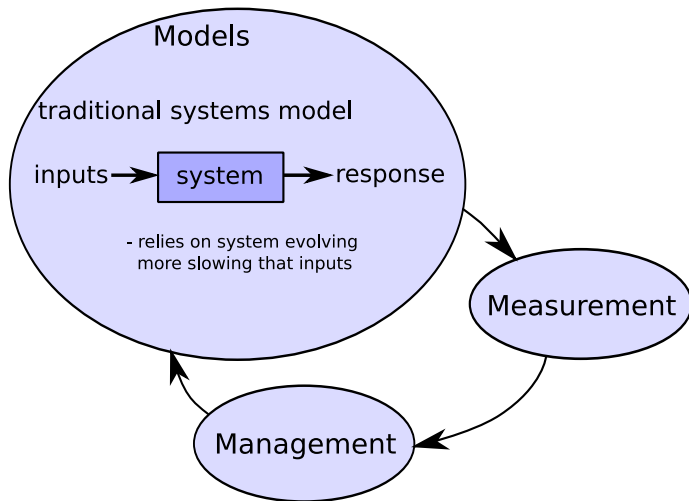
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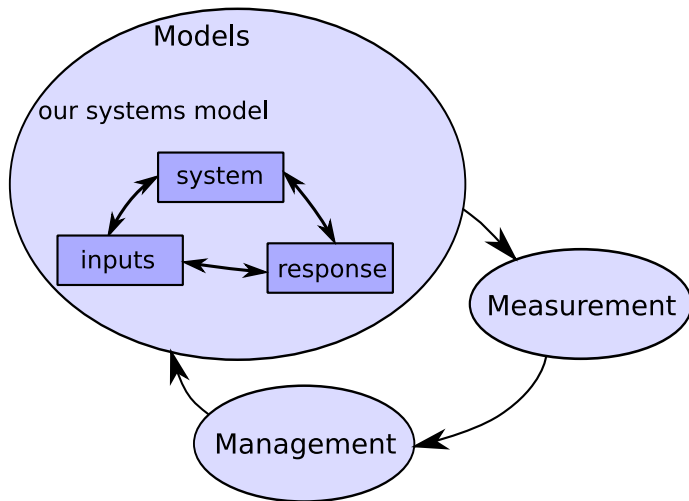
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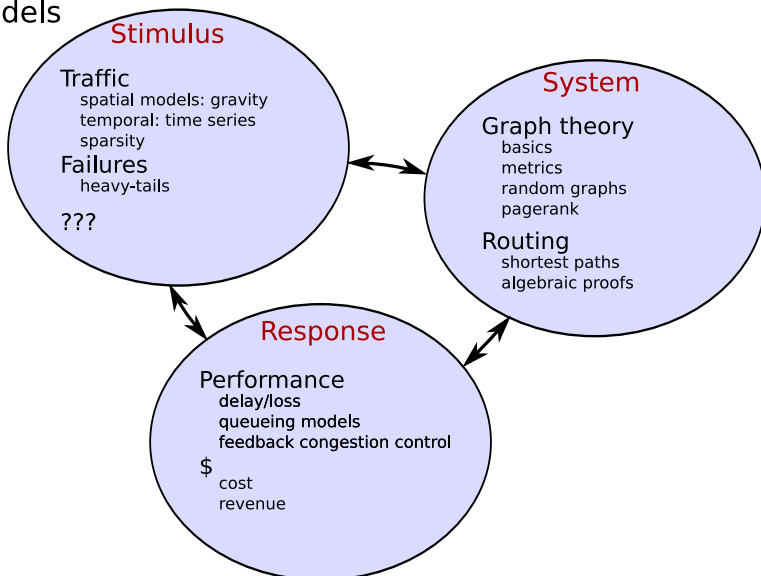


Purpose of our work



Systems model

Models



Why model

- simulations: particularly of higher-level phenomena or algorithms, or to test “what if” scenarios.
- extrapolation: consider what will happen as the network grows.
- sampling: understand the impact of sampling the graph.
- similarity: compare graphs
- visualisation and compression: how can we understand something too big to look at all at once.
- anonymization: we might not be able to publish data due to privacy, but we may be able to publish the model.
- structure: model can teach us about network structure and formation (maybe)
- null-model: a starting point to test hypotheses

Features of a good (random graph) model

- Can generate an ensemble
 - ▶ controlled variation
 - ▶ needed for statistics
- Captures real constraints and costs
 - ▶ otherwise results could be silly
- Prefer operationally meaningful parameters
 - ▶ prefer \$5 per mile to $\beta = 3.4$
- Tunability
 - ▶ want to be able to control output
 - ▶ transparent relationship between inputs and outputs
- Parameters should be measurable/estimatable
- Should generate a network, not just a graph
 - ▶ links and nodes have features
 - ★ e.g., link capacity and distance
- “Everything should be made as simple as it can be — but not simpler.”
 - Attributed to A. Einstein
- Scalability to large networks

Realism, accuracy and fidelity

- Often “realism” means “we fit our favourite statistics”
 - ▶ you have seen a taste of how many stats there are for networks
 - ▶ people keep coming up with more
 - ▶ if you invent enough, you can always find one that fits
- We favour the idea that
 - ▶ it can fit statistics
 - ▶ but it must have a physically realistic model as well

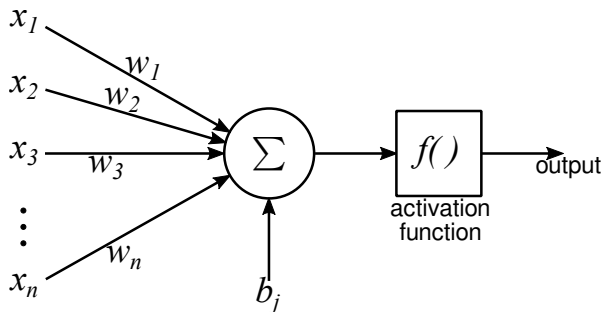
Section 2

Application: Artificial Neural Networks

Neural Networks

- Biological Neural Networks
 - ▶ *e.g., c. elegans*
- Artificial Neural Networks (ANNs)
 - ▶ used to understand how biological neural networks work
 - ▶ used to duplicate our cognitive abilities
 - ★ often under the broader heading of Machine Learning (ML)

Artificial Neurons



- Model a “neuron” as follows:
 - ▶ take the sum of weighted (real) inputs x_i , and bias b_j
 - ▶ pass it through a *activation* function $f(\cdot)$
- Result

$$y_j = f \left(b_j + \sum_{i=1}^n w_i x_i \right)$$

Activation functions

- A common activation function is the *sigmoid*

$$f(x) = \frac{1}{1 + \exp(-x)}$$

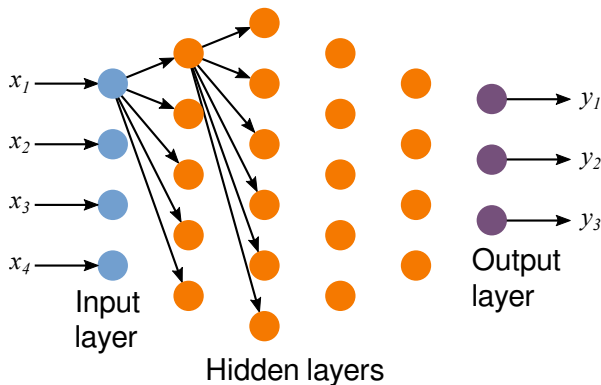
- There are many others:
 - ▶ hyperbolic tangent
 - ▶ hard threshold (step function)
- Reasons for choices
 - ▶ simple
 - ▶ differentiable
 - ▶ maps to values in $[0, 1]$
 - ▶ *non-linear*

Artificial Neural *Network*

- Now put these “neurons” together into a network
- Various organisations
- Commonalities
 - ▶ directed
 - ▶ usually organised in layers
 - ★ multipartite – typically links between one layer to the next (only)
 - ★ could be links crossing between layers, or backwards
 - ▶ highly structured, repeated patterns
 - ▶ other variations:
 - ★ acyclic: also called *feed forward*
 - ★ but can be “recurrent”, e.g., Hopfield networks

The Multi-layer Perceptron (MLP)

- Perceptron is one of the earliest (1957), and best known networks
 - ▶ basically the single neuron above
 - ▶ can't do that much by itself
- Multi-layer perceptron: link all in layer i to all in $i + 1$



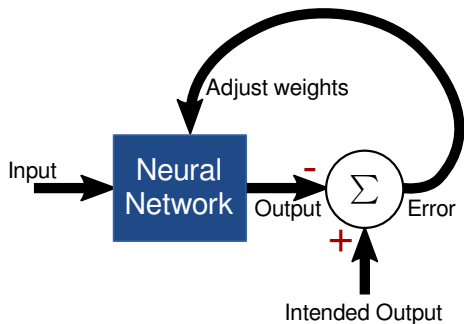
- Convolutional Neural Net (CNN) is similar

Pattern Recognition

- Pattern recognition is a VERY important part of “thinking”
- In essence, we can model pattern recognition as a function mapping a set of inputs, to an output
 - ▶ classification: output is the class of the input
- *Universal Approximation Theorem* states (roughly) that a MLP can model any such function with arbitrary precision (given enough nodes)
- Note that if $f(\cdot)$ were linear, then the network would just be a big linear combination, which would be pretty boring, but some linear pieces are OK
- *Deep learning* is called this because lots of layers (deep)

Training an ANN

- Training is just
 - ▶ set of inputs and desired outputs
 - ★ think of these as defining a function $\mathbb{R}^n \rightarrow \mathbb{R}$
 - ▶ optimising the weights on each link such that the neural network has the best possible approximation to the training function
 - ▶ often done by *reinforcement learning*, i.e., repeated iteration



Training an ANN

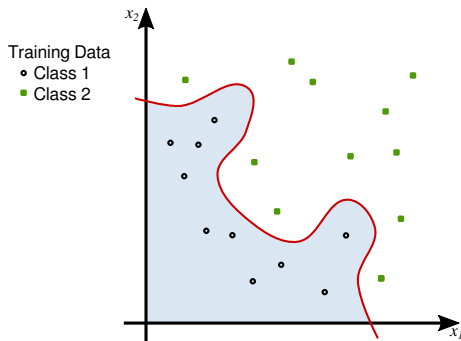
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- This is harder to do than it sounds
 - ▶ you could need LOTS of training data to define the function with enough resolution
 - ▶ noise in training data
 - ▶ there are LOTS of weights forming your optimisation variable, hence computational cost
 - ▶ no guarantee (in general) that it will be a “nice” optimisation problem, e.g., a convex program
 - ▶ over-fitting
- Perceptron training relatively straightforward
 - ▶ back-propagation
 - ▶ but not that relevant to this course, so I leave it to you to find out more

What can we say about these networks?

- By default, they tend to be dense
 - ▶ can improve performance sometimes by “sparsifying”, *i.e.*, removing links that don’t contribute a lot
 - ▶ use locality in the input to remove some edges
- Substructure
 - ▶ often some locality (neurons relate to a position in space, and more connections between close nodes)
 - ▶ some layers are *convolutional* – convolve outputs of a group from prior layer
 - ▶ some layers are *pooling* – pool outputs of a larger group
- They have very repetitive structures
 - ▶ more on this next week

Simple Example

Classification is a very common ML task

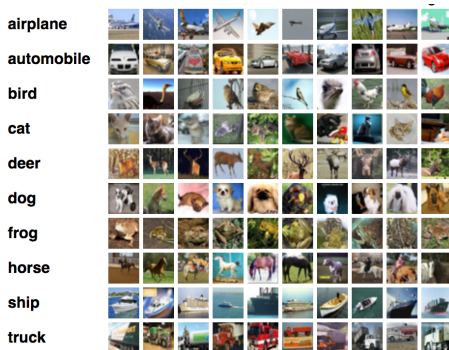


Function to learn

$$g(\mathbf{x}) = \begin{cases} 1, & \text{inside shaded region} \\ 2, & \text{outside shaded region} \end{cases}$$

Slightly Harder Example

Input



But images are complex, so we construct a large set of *features* (i.e., numbers) to describe each image. Perhaps as detailed as the value of each pixel.

“Deep Learning” Examples

Deep learning uses many-layered ANNs

- Google Neural Machine Translation
<https://ai.googleblog.com/2016/09/a-neural-network-for-machine.html>
<https://arxiv.org/abs/1609.08144>
8 encoder, and 8 decoder layers, 36 M sentences used in training, 6 days of training using 96 Nvidia GPUs
- DeepMind WaveNet, synthesizes speech
<https://deepmind.com/blog/wavenet-generative-model-raw-audio/>
<https://arxiv.org/pdf/1609.03499.pdf>
8 layers, 44 hours speech in training
- Google Quickdraw
<https://quickdraw.withgoogle.com/>, recognises sketches
50 million drawings for training

Do we learn about our brain from ANNs?

- ANNs work, but they are very like “black boxes” in that they don't explain why they work
- Artificial neurons intended to model real neurons
 - ▶ dendrites bring input signals from other neurons
 - ▶ soma acts to sum inputs
 - ▶ axon sends pulse when activated

But real neurons “fire” in discrete pulses

- Networks in ANNs are often
 - ▶ very regular
 - ▶ size
 - ★ our brain has 86 billion neurons
 - ★ biggest “deep learners” 160 billion *parameter*
 - ★ even our gut has \sim 500 million neurons
 - ▶ our brain does other things, e.g., consciousness

Further reading I