## Example: the Catenary, again

## Variational Methods \& Optimal Control

lecture 13

Matthew Roughan
[matthew.roughan@adelaide.edu.au](mailto:matthew.roughan@adelaide.edu.au)
Discipline of Applied Mathematics
School of Mathematical Sciences
University of Adelaide

April 14, 2016

## Numerical solutions (continued)

Ritz applied to the catenary gives additional insights and Kantorovich's method generalizes Ritz to 2D functions..

The functional of interest (the potential energy) is

$$
W_{p}\{y\}=m g \int_{x_{0}}^{x_{1}} y \sqrt{1+y^{\prime 2}} d x
$$

Take symmetric problem with fixed end points

$$
y(-1)=a \text { and } y(1)=a
$$

and we know the solution looks like

$$
y(x)=c_{1} \cosh \left(\frac{x}{c_{1}}\right)
$$

where $c_{1}$ is chosen to match the end points.

Example: the Catenary, again

$$
y(1)=2 \text { gives } c_{1}=0.47 \text { or } c_{1}=1.697
$$

- are they both local minima?



## Ritz and the Catenary

Lets try approximating the curve by a polynomial

$$
y(x)=a_{0}+a_{1} x+a_{2} x^{2}+a_{3} x^{3}+a_{4} x^{4}+\cdots
$$

Note that symmetry of problem implies $y$ is an even function, and hence the odd terms $a_{1}=a_{3}=\cdots=0$. So, to second order we can approximate

$$
y(x) \simeq a_{0}+a_{2} x^{2}
$$

We have fixed $y(1)=y_{1}$, so we can simplify to get

$$
y(x) \simeq a_{0}+\left(y_{1}-a_{0}\right) x^{2}
$$

Variational Methods \& Optimal Control: lecture 13 - p.5/22

## Ritz and the Catenary

$$
\begin{aligned}
y & \simeq a_{0}+\left(y_{1}-a_{0}\right) x^{2} \\
y^{\prime} & \simeq 2\left(y_{1}-a_{0}\right) x
\end{aligned}
$$

We can substitute into the functional

$$
W_{p}\{y\}=m g \int_{x_{0}}^{x_{1}} y \sqrt{1+y^{\prime 2}} d x
$$

and integrate to get a function $W_{p}\left(a_{1}\right)$ with respect to $a_{0}$.
But this function is pretty complicated

## Ritz and the Catenary

From Maple

$$
\begin{aligned}
& W_{p}\left(a_{0}\right)=-1 / 4 a_{0}\left(-8 \sqrt{\pi}\left(4-4 a_{0}+a_{0}^{2}\right)+\left(-4 \ln (2)-1-\ln \left(4-4 a_{0}+a_{0}^{2}\right)\right) \sqrt{\pi}\right. \\
& -\sqrt{\pi}\left(4-4 a_{0}+a_{0}^{2}\right)\left(-\left(4-4 a_{0}+a_{0}^{2}\right)^{-1}-8\right) \\
& -8 \sqrt{\pi}\left(4-4 a_{0}+a_{0}^{2}\right) \operatorname{sqrt}\left(1+\left(16-16 a_{0}+4 a_{0}^{2}\right)^{-1}\right) \\
& \left.-1 / 16 \frac{\left.\sqrt{\pi}\left(128-128 a_{0}+32 a_{0}\right)^{2}\right) \ln \left(1 / 2+1 / 2 \operatorname{sqrq}\left(1+\left(16-16 a_{0}+4 a_{0}^{2}\right)^{-1}\right)\right)}{4-4 a_{0}+a_{0}^{2}}\right)(\sqrt{\pi})^{-1}\left(\operatorname{sqrt}\left(4-4 a_{0}+a_{0}^{2}\right)\right)^{-1} \\
& -1 / 16\left(2-a_{0}\right)\left(-16 \sqrt{\pi}\left(4-4 a_{0}+a_{0}^{2}\right)^{2}-4 \sqrt{\pi}\left(4-4 a_{0}+a_{0}^{2}\right)\right. \\
& -1 / 4\left(1 / 2-4 \ln (2)-\ln \left(4-4 a_{0}+a_{0}^{2}\right)\right) \sqrt{\pi} \\
& +2 \sqrt{\pi}\left(4-4 a_{0}+a_{0}^{2}\right)^{2}\left(1 / 16\left(4-4 a_{0}+a_{0}^{2}\right)^{-2}+2\left(4-4 a_{0}+a_{0}{ }^{2}\right)^{-1}+8\right) \\
& +2 \sqrt{\pi}\left(4-4 a_{0}+a_{0}{ }^{2}\right)^{2}\left(-\left(4-4 a_{0}+a_{0}^{2}\right)^{-1}-8\right) \operatorname{sqrt}\left(1+\left(16-16 a_{0}+4 a_{0}{ }^{2}\right)^{-1}\right) \\
& \left.+1 / 32 \frac{\sqrt{\pi}\left(64-64 a_{0}+16 a_{0}{ }^{2}\right) \ln \left(1 / 2+1 / 2 \operatorname{sqr(t)}\left(1+\left(16-16 a_{0}+4 a_{0}{ }^{2}\right)^{-1}\right)\right)}{4-4 a_{0}+a a_{0}{ }^{2}}\right)\left(4-4 a_{0}+a_{0}{ }^{2}\right)^{-3 / 2} \sqrt{\pi}{ }^{-1}
\end{aligned}
$$

Its a pain to find the zeros of $d W / d a_{0}$, but its easy to plot, and find them numerically.

## Ritz and the Catenary

Its a function, and I can plot it, or use simple numerical techniques to find its stationary points.


## Ritz and the Catenary

Stationary points

- local max: $a_{0} \simeq 0.41$
- local min: $a_{0} \simeq 1.69$


Variational Methods \& Optimal Control: lecture 13 - p.9/22

## Ritz and the Catenary

Doesn't just give us an approximation to the extremal curves, its also gives us some insight into the nature of these extremals. If

- approximations are near to the actual extrema
- There are no other extrema so close by
- The functional is smooth (it can't have jumps either)

Then the type of extrema we get for the approximation will be the same for the real extrema, i.e.,

- local max: $a_{0} \simeq 0.41 \Rightarrow$ local max for $c_{1}=0.47$
- local min: $a_{0} \simeq 1.69 \Rightarrow$ local $\min$ for $c_{1}=1.697$


## More than one indep. var

2D case: we are approximating a surface with series of functions, e.g.

$$
z(x, y) \simeq z_{n}(x, y)=\phi_{0}(x, y)+\sum_{i=1}^{n} c_{i} \phi_{i}(x, y)
$$

where $\phi_{0}(x, y)$ satisfies the boundary conditions, e.g. $\phi_{0}(x, y)=z_{0}(x, y)$ for $(x, y) \in \delta \Omega$, the boundary of the region on interest $\Omega$, and the $\phi_{i}(x, y)$ satisfy the homogeneous boundary conditions $\phi_{i}(x, y)=0$ for $(x, y) \in \delta \Omega$.

[^0]
## More than one indep. var

As before, we approximate the functional by

$$
F\{z\} \simeq F\left\{z_{n}\right\}=F_{n}\left(c_{1}, \ldots, c_{n}\right)
$$

As before we determine the $c_{j}$ by requiring that the partial derivatives are zero, e.g.

$$
\frac{\partial F_{n}}{\partial c_{i}}=0
$$

for all $i=1,2, \ldots, n$

## Kantorovich's method

Approximate with

$$
z(x, y) \simeq z_{n}(x, y)=\phi_{0}(x, y)+\sum_{i=1}^{n} c_{i}(x) \phi_{i}(x, y)
$$

Again the $\phi_{i}$ are suitably chosen, but the $c_{i}$ are no longer constants, but rather functions of one independent variable. This allows a larger class of functions to be used.

## Kantorovich's method

Note that the integral function

$$
F\left\{z_{n}\right\}=\iint_{\Omega} z_{n}(x, y) d x d y=\sum_{i=0}^{n} \int c_{i}(x)\left[\int_{y_{0}(x)}^{y_{1}(x)} \phi_{i}(x, y) d y\right] d x
$$

We integrate the inner integral, and get

$$
F\left\{z_{n}\right\}=\sum_{i=0}^{n} \int c_{i}(x) \Phi_{i}(x) d x
$$

Now we just have a function of $x$, and so we may apply the Euler-Lagrange machinery.

The method approx. separates the variables $x$ and $y$.

## Example

Find the extremals of

$$
F\{z(x, y)\}=\int_{-b}^{b} \int_{-a}^{a}\left(z_{x}^{2}+z_{y}^{2}-2 z\right) d x d y
$$

with $z=0$ on the boundary.
The Euler-Lagrange equation reduces to the Poisson equation, e.g.

$$
\begin{aligned}
\frac{d}{d x} \frac{\partial f}{\partial z_{x}}+\frac{d}{d x} \frac{\partial f}{\partial z_{x}} & =\frac{\partial f}{\partial z} \\
\frac{d}{d x} 2 z_{x}+\frac{d}{d x} 2 z_{y} & =-2 \\
\nabla^{2} z(x, y) & =-1
\end{aligned}
$$

## Example

Approximate

$$
z_{1}(x, y)=c(x)\left(b^{2}-y^{2}\right)
$$

Note $z_{1}(x, \pm b)=0$ (as required) and

$$
\begin{aligned}
\left(\frac{\partial z_{1}}{\partial x}\right)^{2} & =\left(c^{\prime}(x)\left(b^{2}-y^{2}\right)\right)^{2} \\
& =c^{\prime}(x)^{2}\left(b^{4}-2 b^{2} y^{2}+y^{4}\right) \\
\left(\frac{\partial z_{1}}{\partial y}\right)^{2} & =(c(x) 2 y)^{2} \\
& =4 c(x)^{2} y^{2}
\end{aligned}
$$

## Example

Hence, we approximate

$$
\begin{aligned}
\{z(x, y)\} & \simeq F\left\{z_{1}(x, y)\right\} \\
& =\int_{-b}^{b} \int_{-a}^{a}\left(z_{x}^{2}+z_{y}^{2}-2 z\right) d x d y \\
& =\int_{-a}^{a}\left[\int_{-b}^{b}\left[c^{\prime}(x)^{2}\left(b^{2}-y^{2}\right)^{2}+4 c(x)^{2} y^{2}-2 c(x)\left(b^{2}-y^{2}\right)\right] d y\right] d x \\
& =\int_{-a}^{a}\left[c^{\prime}(x)^{2}\left(b^{4} y-2 b^{2} y^{3} / 3+y^{5} / 5\right)+4 c(x)^{2} y^{3} / 3-\right. \\
& \left.2 c(x)\left(b^{2} y-y^{3} / 3\right)\right]_{-b}^{b} d x \\
& =\int_{-a}^{a}\left[\frac{16}{15} b^{5} c^{\prime}(x)^{2}+\frac{8}{3} b^{3} c(x)^{2}-\frac{8}{3} b^{3} c(x)\right] d x
\end{aligned}
$$

|  | Variational Methods \& Optimal Control: lecture $13-$ p. $17 / 22$ |
| :--- | :--- |

## Example

So we can write

$$
F\{z(x, y)\} \simeq F\left\{z_{1}(x, y)\right\}=F\{c(x)\}=\int_{-a}^{a} f\left(x, c, c^{\prime}\right) d x
$$

We can use the simple Euler-Lagrange equations, where

$$
\begin{aligned}
f\left(x, c, c^{\prime}\right) & =\frac{16}{15} b^{5} c^{\prime}(x)^{2}+\frac{8}{3} b^{3} c(x)^{2}-\frac{8}{3} b^{3} c(x) \\
\frac{\partial f}{\partial c} & =\frac{16}{3} b^{3} c(x)-\frac{8}{3} b^{3} \\
\frac{\partial f}{\partial c^{\prime}} & =\frac{32}{15} b^{5} c^{\prime}(x) \\
\frac{d}{d x} \frac{\partial f}{\partial c^{\prime}} & =\frac{32}{15} b^{5} c^{\prime \prime}(x)
\end{aligned}
$$

## Example

Euler-Lagrange equations

$$
\begin{aligned}
\frac{d}{d x} \frac{\partial f}{\partial c^{\prime}}-\frac{\partial f}{\partial c} & =0 \\
\frac{32}{15} b^{5} c^{\prime \prime}(x)-\frac{16}{3} b^{3} c(x)+\frac{8}{3} b^{3} & =0 \\
c^{\prime \prime}(x)-\frac{5}{2 b^{2}} c(x) & =-\frac{5}{4 b^{2}}
\end{aligned}
$$

Solutions

$$
c(x)=k_{1} \cosh \left(\sqrt{\frac{5}{2}} \frac{x}{b}\right)+k_{2} \sinh \left(\sqrt{\frac{5}{2}} \frac{x}{b}\right)+\frac{1}{2}
$$

## Example

Note that the function must be zero on the boundary so $z( \pm a, y)=0$, and so we look for an even function $c(x)$, and so $k_{2}=0$, and also $c( \pm a)=0$, so

$$
\begin{aligned}
c(a) & =k_{1} \cosh \left(\sqrt{\frac{5}{2}} \frac{a}{b}\right)+\frac{1}{2} \\
-\frac{1}{2} & =k_{1} \cosh \left(\sqrt{\frac{5}{2}} \frac{a}{b}\right) \\
k_{1} & =-\frac{1}{2 \cosh \left(\sqrt{\frac{5}{2}} \frac{a}{b}\right)}
\end{aligned}
$$

## Example

Solution

$$
z_{1}(x, y)=\frac{1}{2}\left(b^{2}-y^{2}\right)\left(1-\frac{\cosh \left(\sqrt{\frac{5}{2}} \frac{x}{b}\right)}{\cosh \left(\sqrt{\frac{5}{2}} \frac{a}{b}\right)}\right)
$$

If we wanted a more exact approximation, we could try

$$
z_{2}(x, y)=\left(b^{2}-y^{2}\right) c_{1}(x)+\left(b^{2}-y^{2}\right)^{2} c_{2}(x)
$$

## Lower bounds

- Obviously, quality of solution depends on
$\triangleright$ family of functions chosen
$\triangleright$ number of terms used, $n$
- Could test convergence by increasing $n$ and seeing the difference in $\left|F\left\{y_{n+1}\right\}-F\left\{y_{n}\right\}\right|$, but this is not guaranteed to be a good indication.
- A better way to assess convergence is to have a lower-bound

$$
\text { lower bound } \leq F\{y\} \leq \text { upper bound }
$$

- use complementary variation principle
- but its a bit complicated for us to cover here.


[^0]:    Variational Methods \& Optimal Control: lecture 13 - p.11/22

