

Malachite: Firewall Policy Comparison

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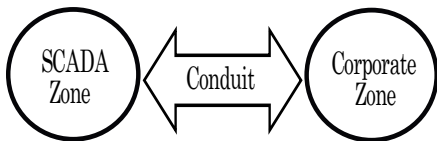
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- Current networks depend on *firewalls* to mitigate cyber attacks
 - especially SCADA networks
- Supervisory Control And Data Acquisition networks
 - core to a nation's critical infrastructure
 - e.g., power, water, wastewater
 - designed for robustness, real-time performance
 - **NOT** secure

- Industry standards exist (eg., Guide to Industrial Control Systems Security by NIST, ANSI/ISA-62443-1-1) for
 - firewall architectures
 - service-specific policies
 - network segregation
- **NO** standards for checking compliance
- Serious firewall misconfigurations are frequent
 - Wool studied 74 corporate firewalls, **>80% had serious errors**
 - we studied 9 real SCADA firewalls, **100% had serious errors**

ANSI/ISA Zone-Conduit model [ANSI/ISA-62443-1-1]:



- **Zone** - groups systems with similar security requirements
 - single zone policy
- **Conduit** - secure communication path between zones
 - firewalls are part of the conduits
- Allows to construct network-wide high-level security policy

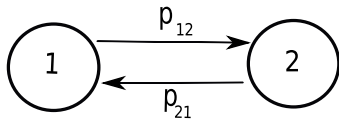
Need automated firewall-policy comparison

- Multiple benefits
 - check best-practice compliance
 - change-impact analysis
 - evaluate multiple policy-designs
- Malachite: mathematical-framework based comparisons
 - precise and unambiguous
 - rule-order independent

Comparison of network policy: a simple example

Implemented firewall policy

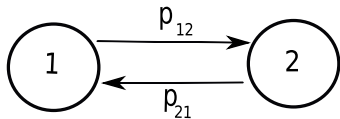
$$\mathcal{P} = (G_1, P_1)$$



Comparison of network policy: a simple example

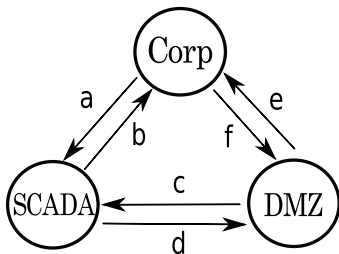
Implemented firewall policy

$$\mathcal{P} = (G_1, P_1)$$



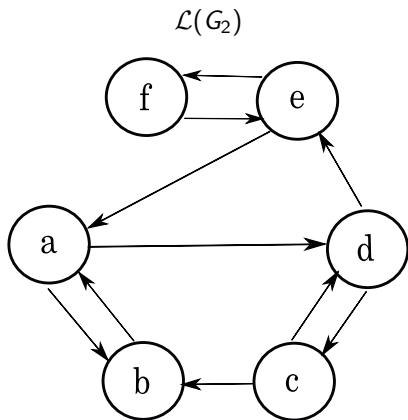
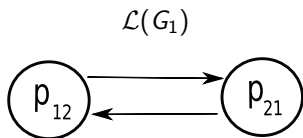
Best-practice firewall policy

$$\mathcal{RP} = (G_2, P_2)$$



- Is \mathcal{P} equally or more restrictive than \mathcal{RP} ?

Workaround: use Line Digraphs (LDs)



- LD isomorphism \implies potential original-graph isomorphism
 - Harary and Norman 1960

- Compliant if *included* or *incorporated* by best-practice policy

Definition (Partial Incorporation)

If $\mathcal{P} = (G_1, P_1)$, $\mathcal{RP} = (G_2, P_2)$, policy \mathcal{RP} partially incorporates \mathcal{P} iff G_1 is a subgraph of G_2 and $\forall e \in G_1, p_1^e \subset p_2^e$. We denote this by $\mathcal{P} \subset \mathcal{RP}(G_1)$.

Is $\mathcal{P} \subset \mathcal{RP}(G1)$? where $\mathcal{P} = (G_1, P_1)$, $\mathcal{RP} = (G_2, P_2)$

1. Derive *semantic partitions* SP_1, SP_2
 - partitions policy into equivalence classes
 - e.g., $SP_1 = \{e_1, e_2\}$; $e_1 = \{p_{12}\}$, $e_2 = \{p_{21}\}$
2. Check $SP_1 \subset SP_2$
3. Find all feasible partition-mappings
4. Construct adjacency matrices A_1, A_2 of LDs per mapping
5. If $A_1 = A_2$ then $\mathcal{P} \subset \mathcal{RP}(G1)$

Application to real SCADA case studies

SUC	Firewalls	Zones	Conduit-policies	Equivalence classes	Maximum class size	\mathcal{RP} Compliant?
1	3	7	22	12	7	✗
2	6	21	162	87	8	✗
3	4	10	34	15	8	✗
4	3	9	32	16	5	✗

- large equivalence class sizes \implies an inefficient network.

- Many obstacles to firewall-policy comparison
- Malachite addresses these challenges
 - network and vendor independent policy semantics
 - derives canonical policies for comparison
- Limitations
 - best practice may not always be correct
 - inclusion/incorporation may not always indicate compliance
 - some human intervention still required

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$$p_A(s) = \begin{cases} s, & \text{if } s \in A, // \textit{accept} \\ \phi, & \text{if } s \in A^c, // \textit{deny}. \end{cases} \quad (1)$$

- $A \subset \mathcal{A}$ where $\mathcal{A} = \{\text{Atomic packet sequences}\}$
- Only consider packet modifications that don't effect other rules (e.g., QoS, TTL changes)
 - no NAT, VPN functionality
 - no creation of packets by rules (e.g., logging)

Zone-Conduit policy snippet

Policy p_0 { Z1 \rightarrow Z2: https, dns;
Z2 \rightarrow Z1: http; }

- Positive, explicit policies conditional on an implicit deny-all rule

Definition (Equivalence)

Two policies p^X and p^Y are equivalent on \mathcal{A} iff $p^X(s) = p^Y(s)$, $\forall s \in \mathcal{A}$. We denote this equivalence by $p^X \equiv p^Y$.

Definition (Inclusion)

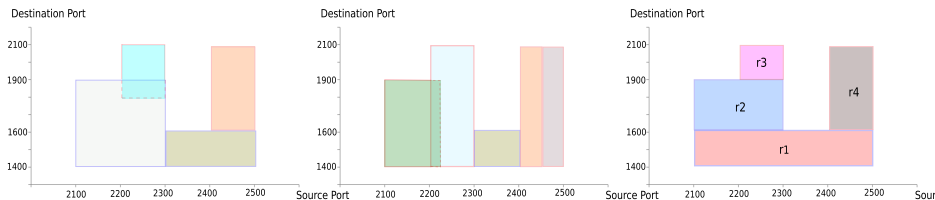
A policy p^X is included in p^Y on \mathcal{A} iff $p^X(s) \in \{p^Y(s), \phi\}$, i.e., X has the same effect as Y on s , or denies s , for all $s \in \mathcal{A}$. We denote inclusion by $p^X \subset p^Y$.

Lemma

Policies $p^X \equiv p^Y$ iff $c(p^X) = c(p^Y)$.

- $c : \Phi \rightarrow \Theta$, where Φ is the policy space and Θ is the canonical space of policies

Canonicalisation of distinct rule sets of a policy



- Policy polygon horizontally partitioned using a Polygon to Rectangle conversion algorithm

Time complexity analysis of policy equivalence

algorithm component	time complexity	comments
cannicalise policy	$O(n)$	$n = \text{policy count}$
construct line digraph	$O(n^2)$	
derive SPs	$O(n^2)$	
check partitions are equal	$O(m^2)$	$m = \text{equiv class count}$
evaluate mappings	$O(\prod_{i=1}^m c_i!)$	$c_i = e_i $

- Worse case time complexity: $O(n!)$, best case: $O(n^2)$

Definition

The semantic partition SP of a set of policies P is given by $SP = \{e_m\}$ where $P = \cup_m e_m$ and the $e_m \subset P$ are the minimal number of equivalence classes, i.e., for all $p_i, p_j \in e_m$ we have $p_i \equiv p_j$.

Definition (plain)

[SP Equivalence and Inclusion] The semantic partitions SP_1 and SP_2 of policies P_1 and P_2 , respectively, are equivalent iff $|SP_1| = |SP_2|$ and $\forall e_1 \in SP_1, \exists e_2 \in SP_2$ such that for any $p_1 \in e_1$ and $p_2 \in e_2$, we have $p_1 \equiv p_2$. We denote this by $SP_1 \equiv SP_2$. Semantic partition SP_1 includes SP_2 iff $\forall e_2 \in SP_2 \exists e_1 \in SP_1$ s.t. $e_2 \subset e_1$. We denote this by $SP_2 \subset SP_1$.

Definition

The semantic difference between policies p^X and p^Y is given by $p^X - p^Y = (p^X \oplus p^Y) \otimes (p^X \otimes p^Y)^c$, where $(p_A)^c = p_{A^c}$ and A^c is A 's complement.

