

# How to Compute Accurate Traffic Matrices for your Network in Seconds

Yin Zhang, Matthew Roughan, Carsten Lund,  
Nick Duffield, Albert Greenberg, Quynh Nguyen  
– AT&T Labs-Research

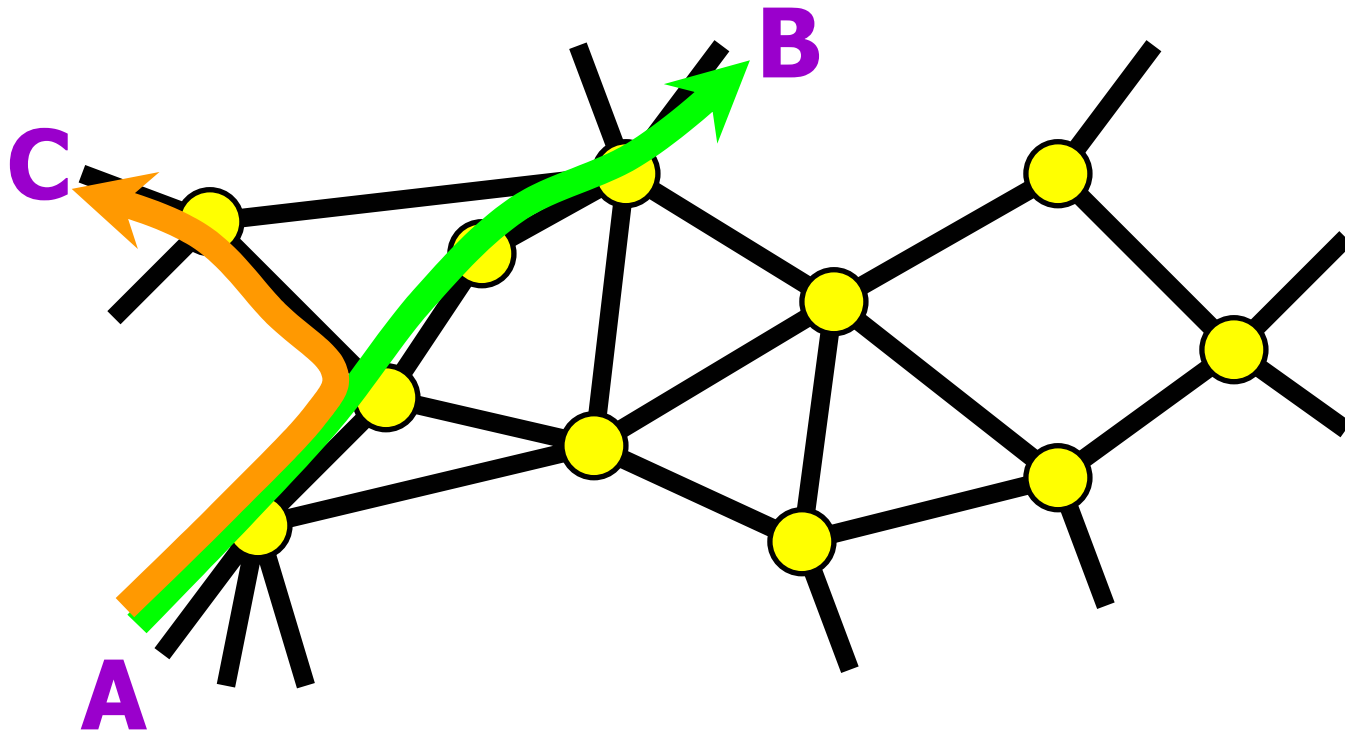
David Donoho – Stanford



# Problem

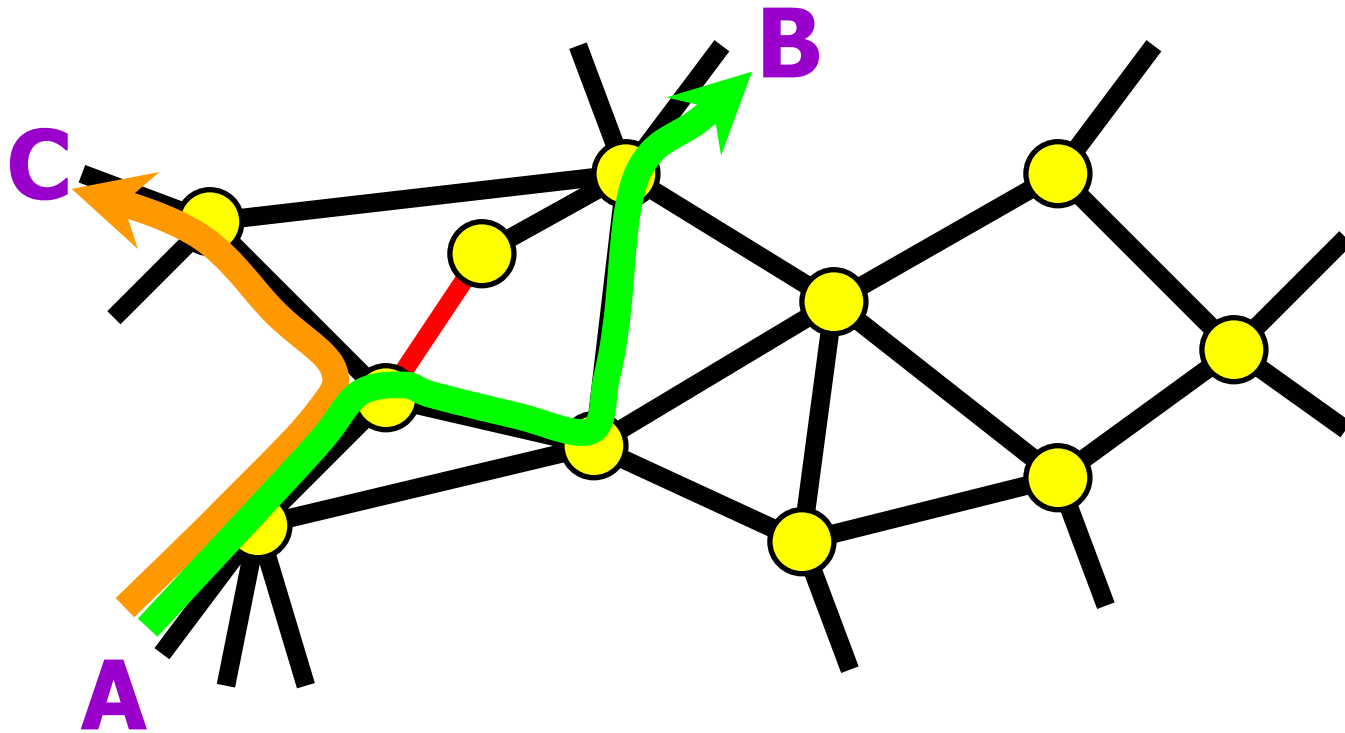
Have link traffic measurements (from SNMP)

Want to know demands from source to destination



# Example App: reliability analysis

Under a link failure, routes change  
want to predict new link loads



# Network Engineering

## ⌘ What you want to do

- ☑ Reliability analysis
- ☑ Traffic engineering
- ☑ Capacity planning

## ⌘ What do you need to know

- ✓ Network and routing
- ✓ Prediction and optimization techniques
- ? Traffic matrix

# Solution: Tomo-gravity

## ⌘ Computes traffic matrices

⊞ input: SNMP, topology, routing policies

## ⌘ Advantages

⊞ Today's data → no special instrumentation

⊞ Fast: a few seconds

⊞ Accurate: average 12% error

⊞ Scales: hundreds of nodes

⊞ Robust: copes easily with data glitches

⊞ Flexible: can incorporate more detailed data

# Tomo-gravity

## Tomography

- ☒ Astronomy
- ☒ Seismology
- ☒ Medical imaging
  - ☒ CAT in CATSCAN

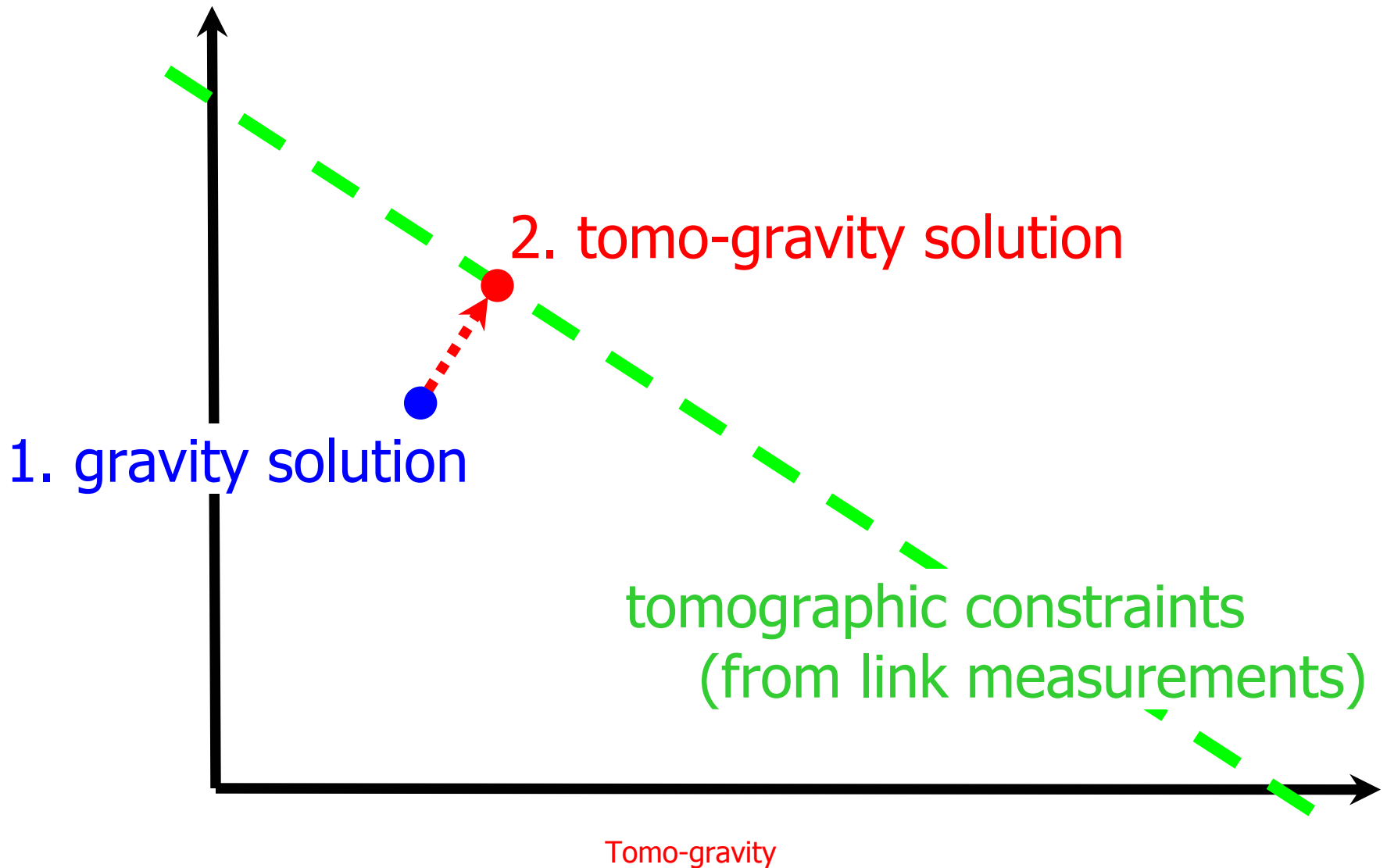
+

## Gravity modeling

- ☒ Econometrics
- ☒ Transportation
  - ☒ planes, trains, automobiles

Foundation: Information Theory

# Tomo-gravity in a Nutshell

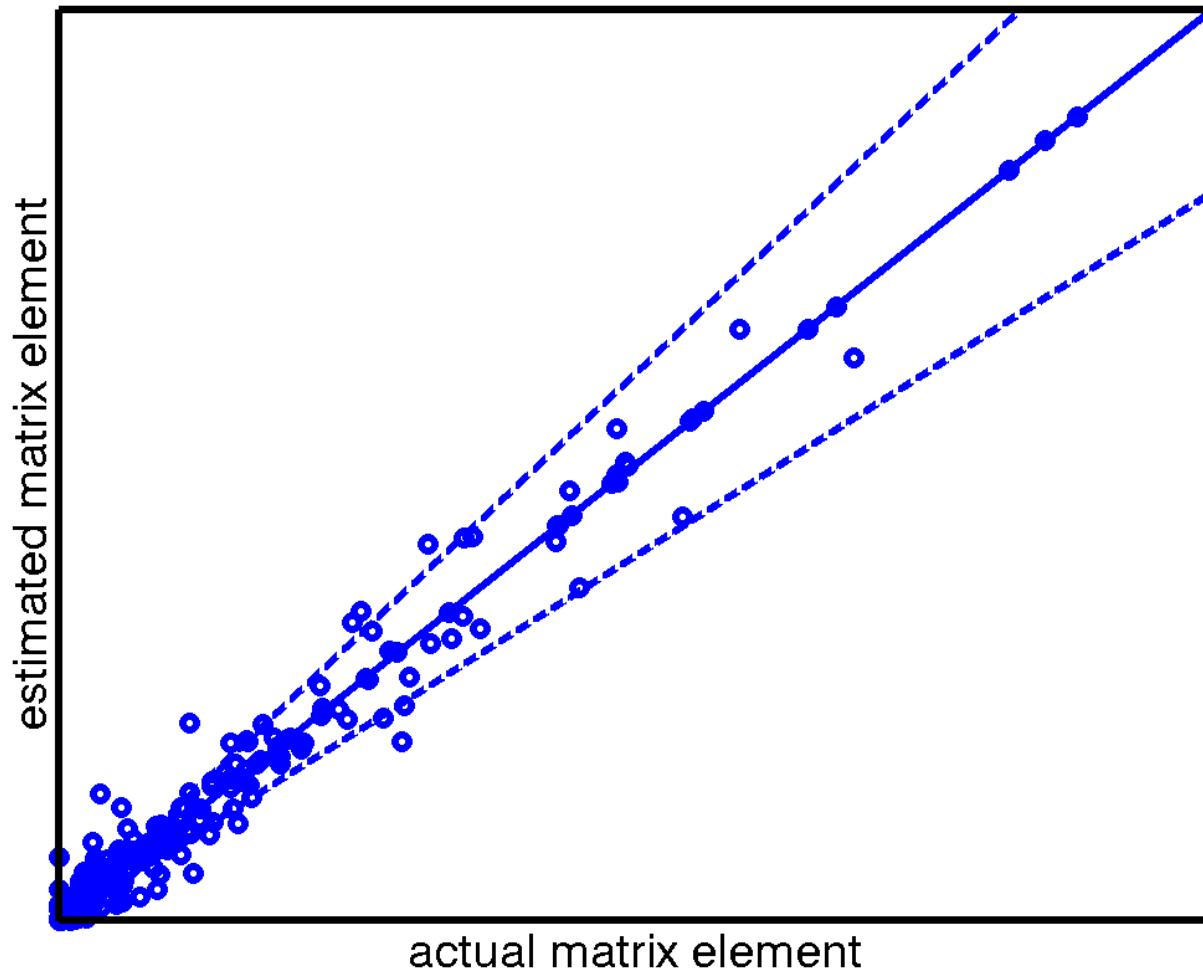


# Tomo-gravity in practice

1. Get topology & routing
2. Measure SNMP link loads
3. Derive gravity solution
  - ⌘ Uses edge loads
4. Compute tomo-gravity solution
  - ⌘ Use internal link data
  - ⌘ Matches observed link loads
  - ⌘ Can incorporate more detailed measurements to boost accuracy

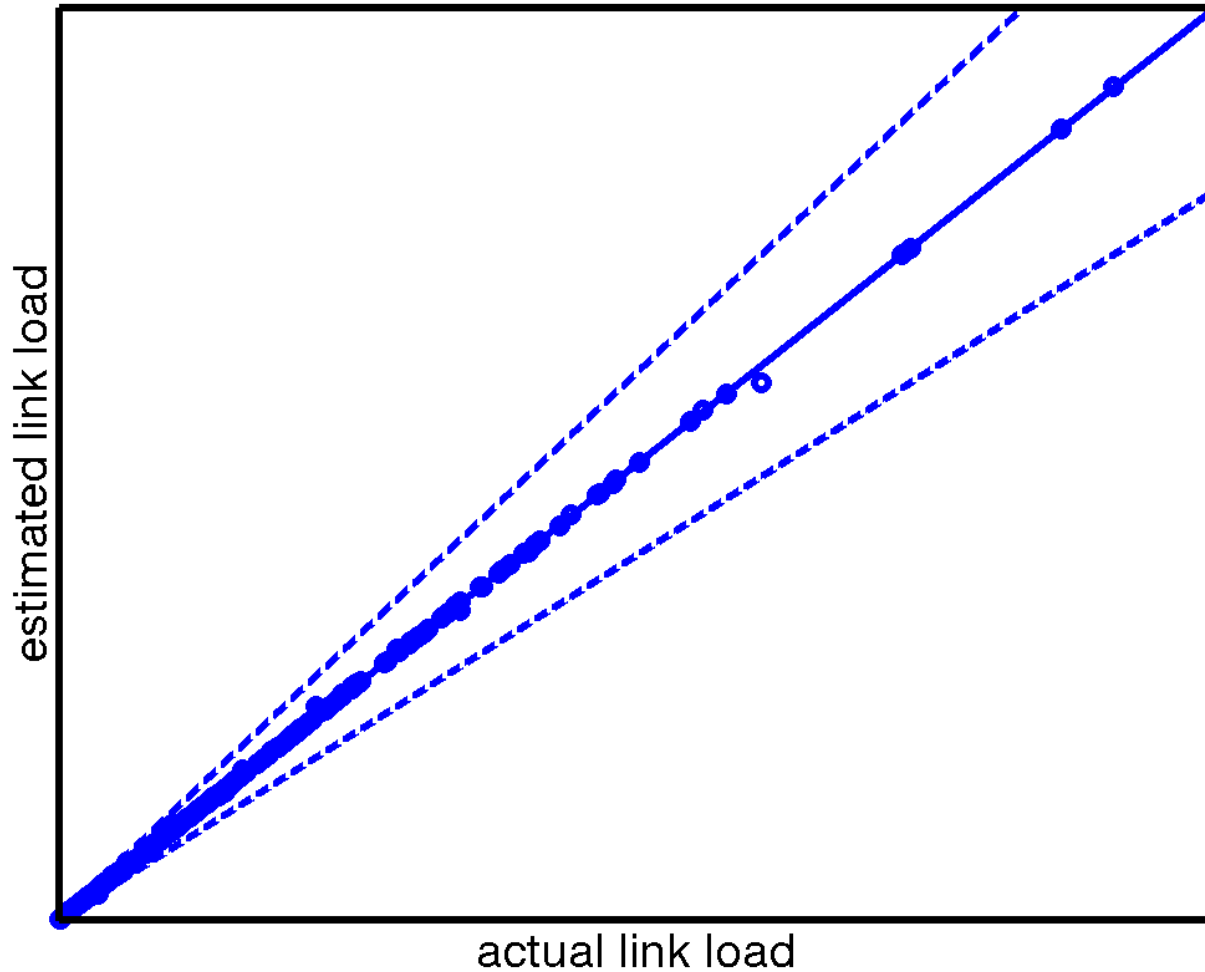


# Real example



lomo-gravity

# Example use: reliability analysis



# Conclusion

## ⌘ Tomo-gravity implemented

- ☑ AT&T's IP backbone (AS 7018)

- ☑ Hourly traffic matrices for > 1 year (in secs)

## ⌘ For a number of applications

- ☑ Reliability analysis (killer app...)

- ☑ Traffic engineering

- ☑ Capacity planning

<http://www.research.att.com/>

[~roughan/tomogravity.html](http://www.research.att.com/~roughan/tomogravity.html)

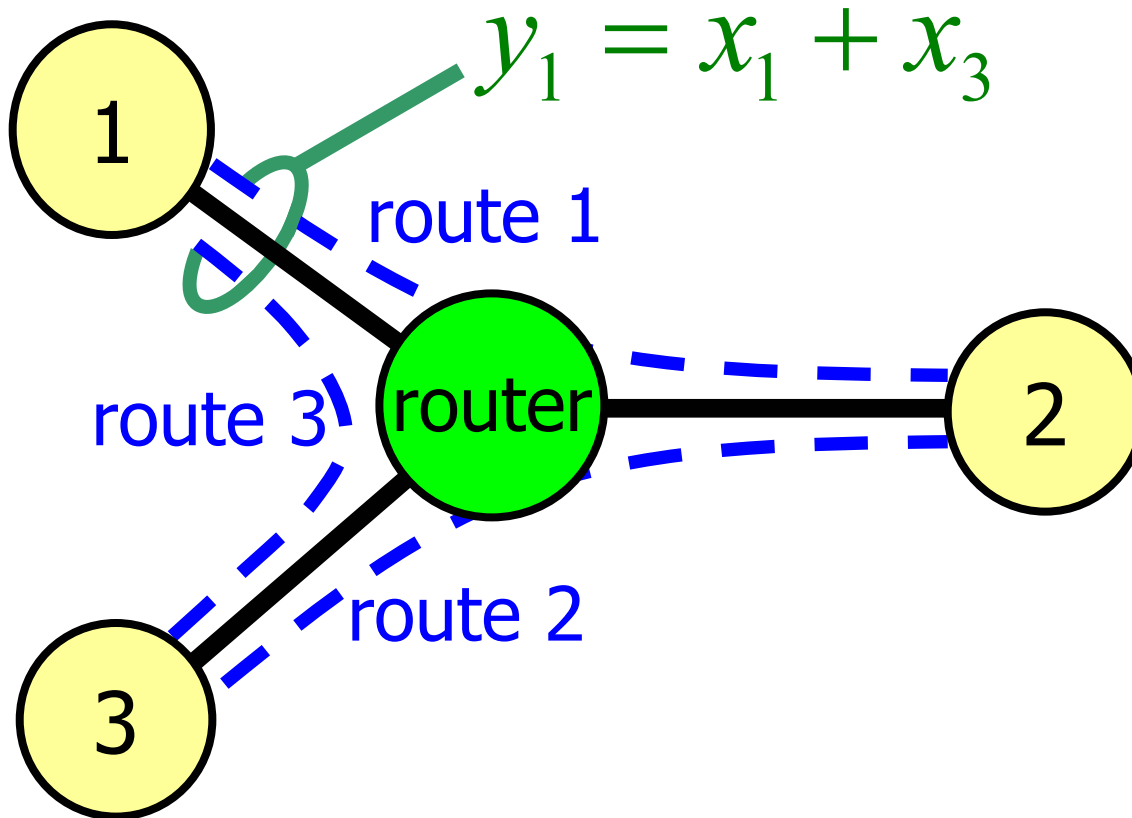
# Key References

- ☒ "Fast, accurate computation of large-scale IP traffic matrices from link measurements", Y.Zhang, M.Roughan, N.Duffield and A.Greenberg, ACM SIGMETRICS 2003.
- ☒ "An information theoretic approach to traffic matrix estimation", Y.Zhang, M.Roughan, C.Lund and D.Donoho, ACM SIGCOMM 2003.
- ☒ Both available at <http://www.research.att.com/~roughan/papers.html>



# Additional Slides

# Mathematical Formalism



# Equations

$$Y = AX$$

Link measurements

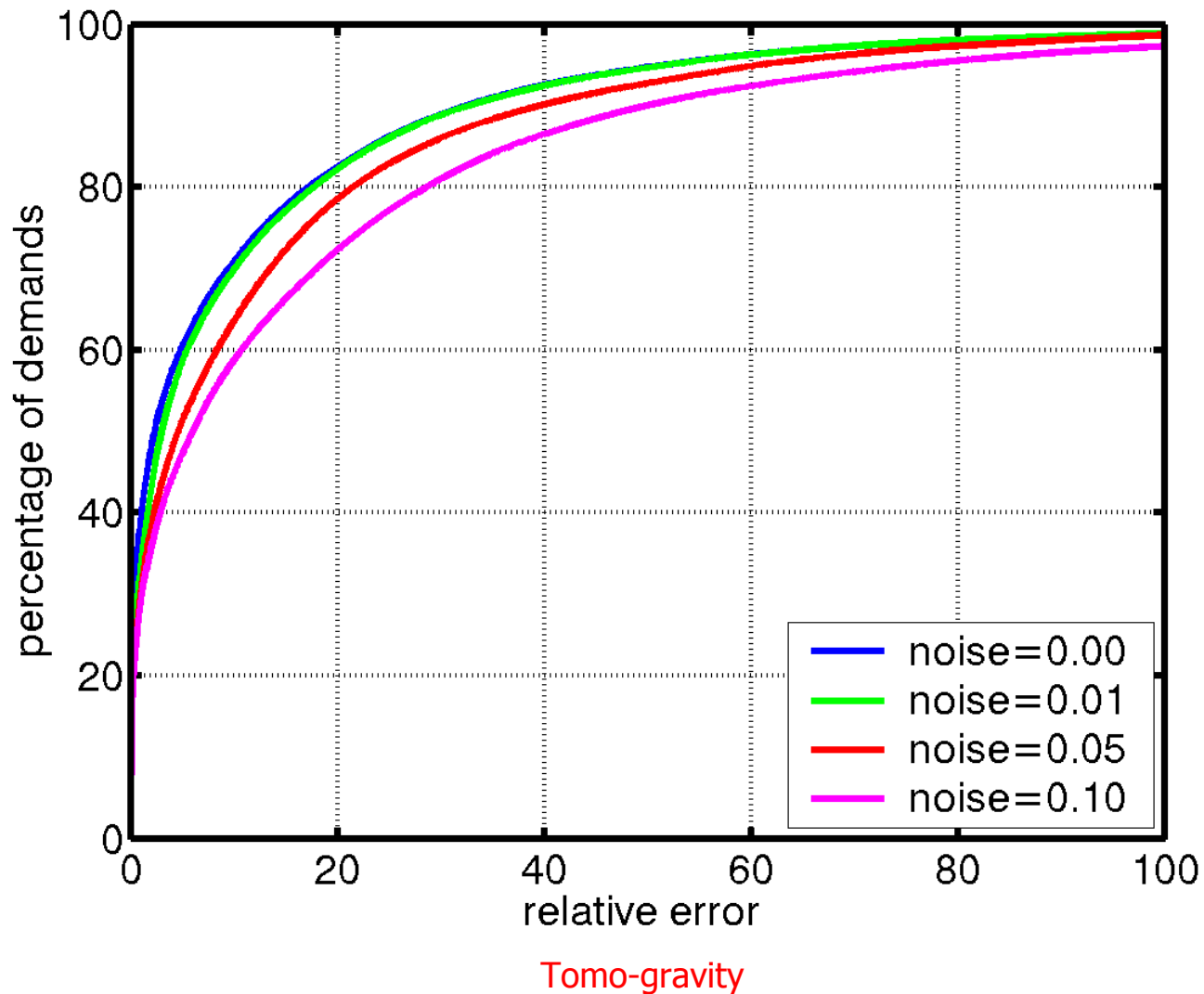
Traffic matrix

Routing matrix

The diagram shows the equation  $Y = AX$  in blue. Three black arrows point from text labels to the variables: 'Link measurements' points to  $Y$ , 'Traffic matrix' points to  $X$ , and 'Routing matrix' points to  $A$ .

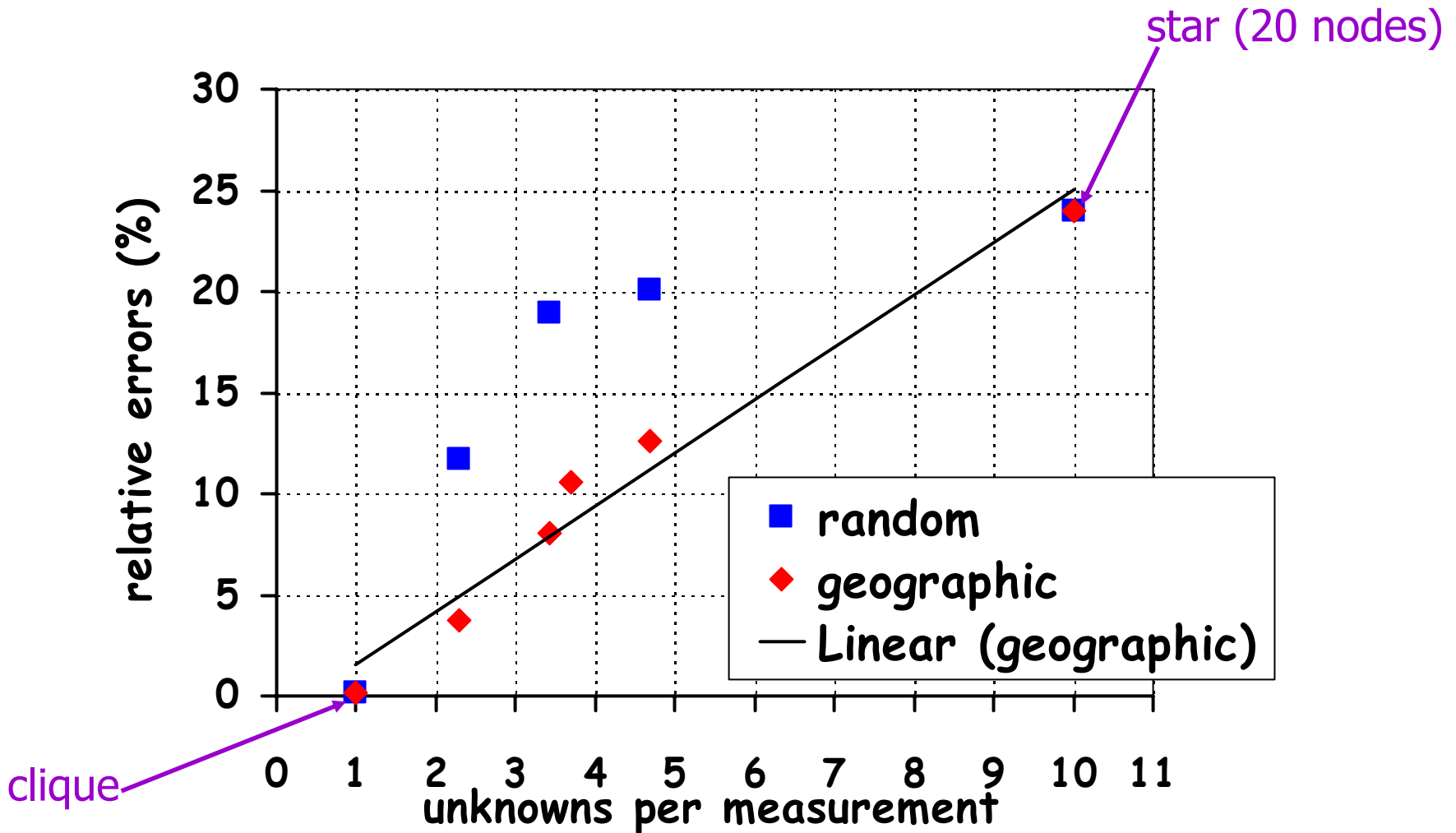
Many more unknowns than measurements

# Robustness (input errors)

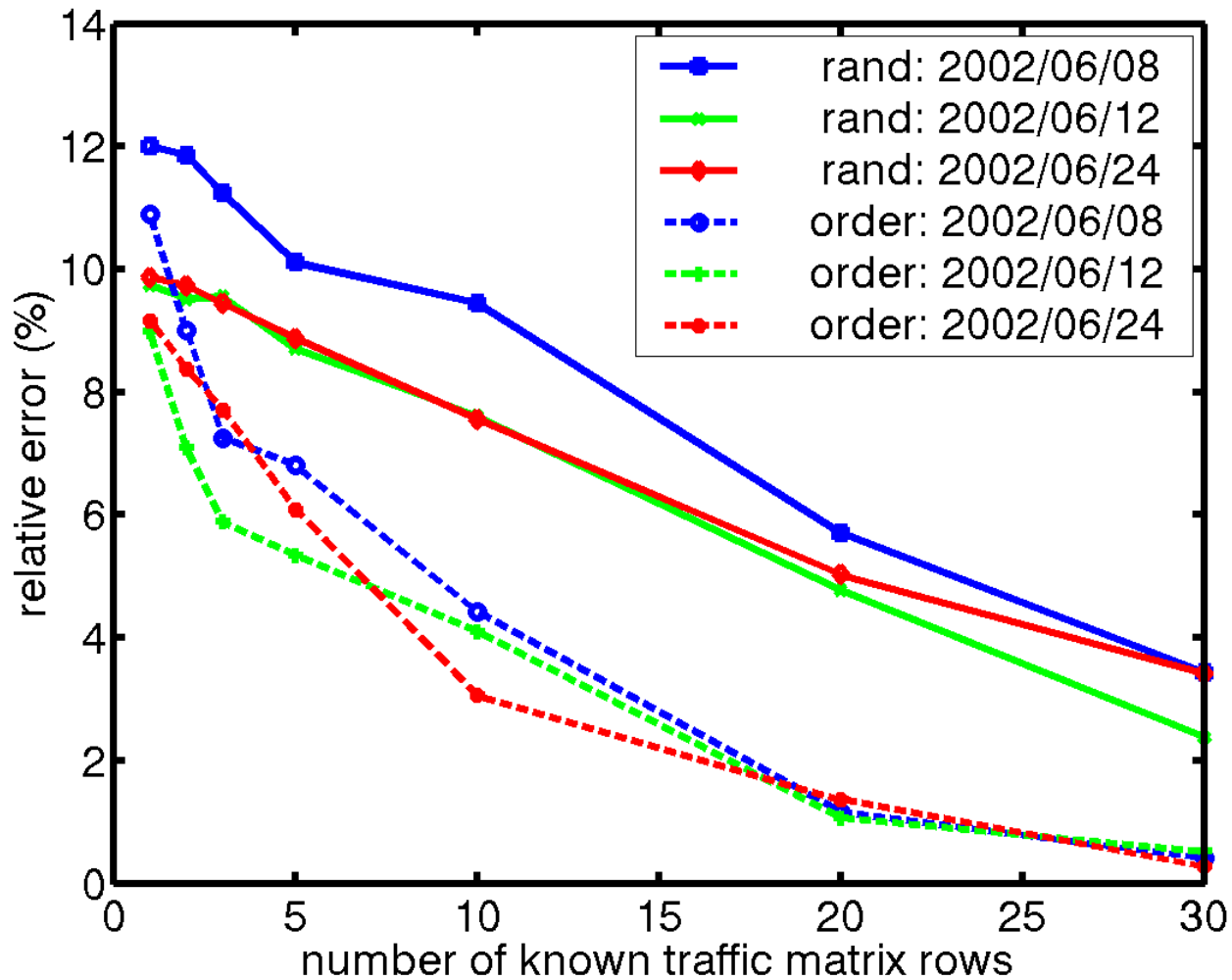




# Dependence on Topology

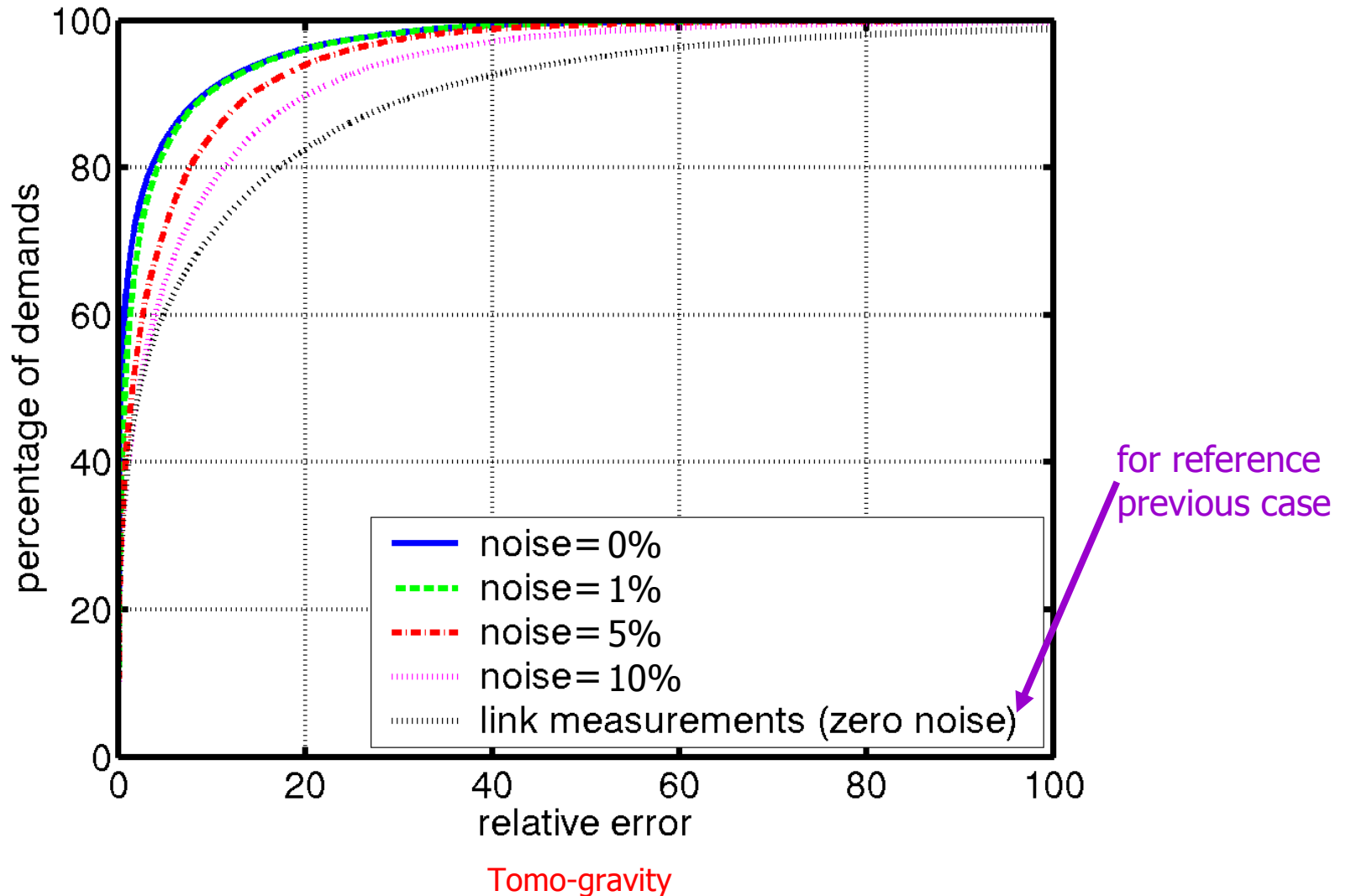


# Additional information - Netflow

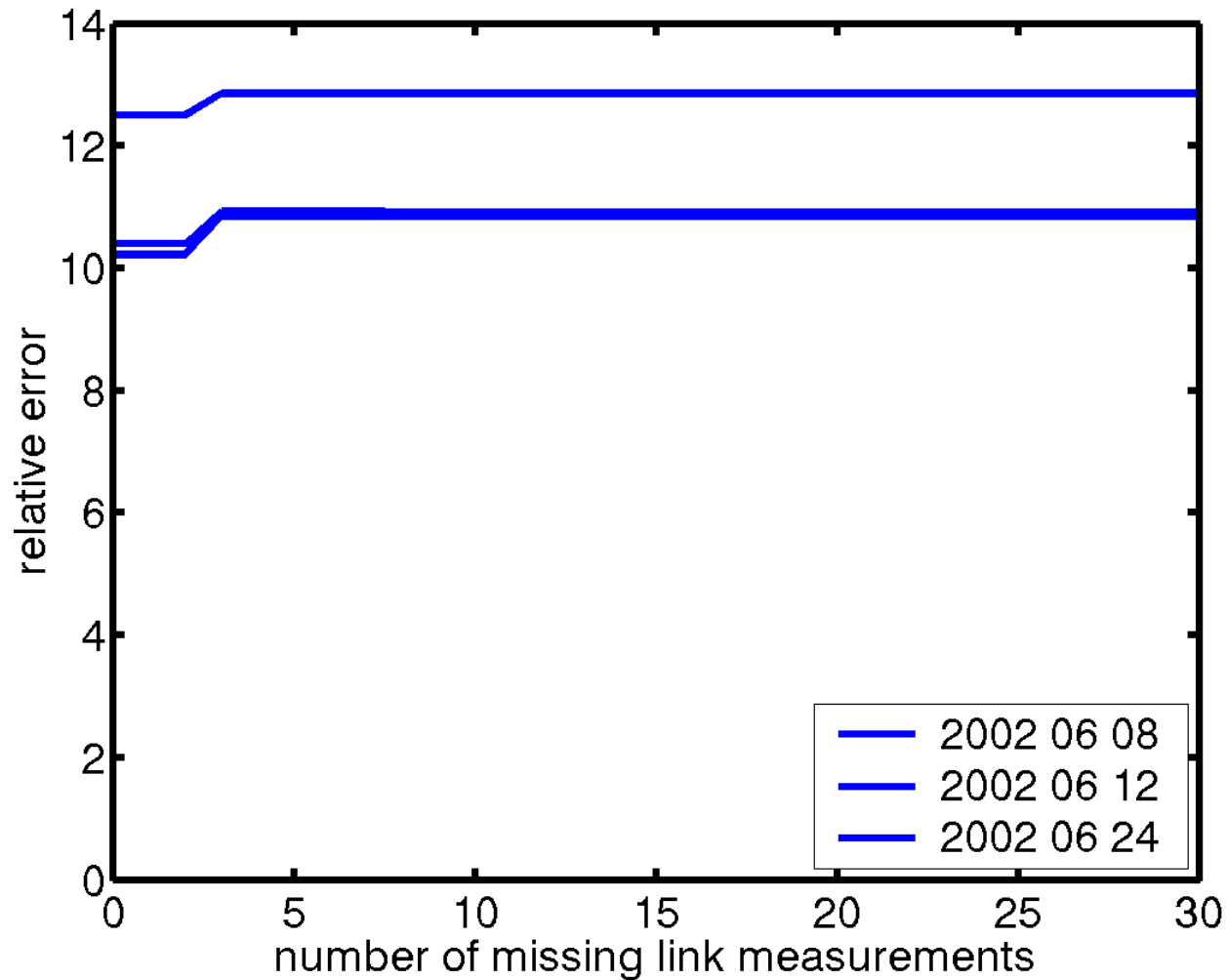


Tomo-gravity

# Local traffic matrix (George Varghese)



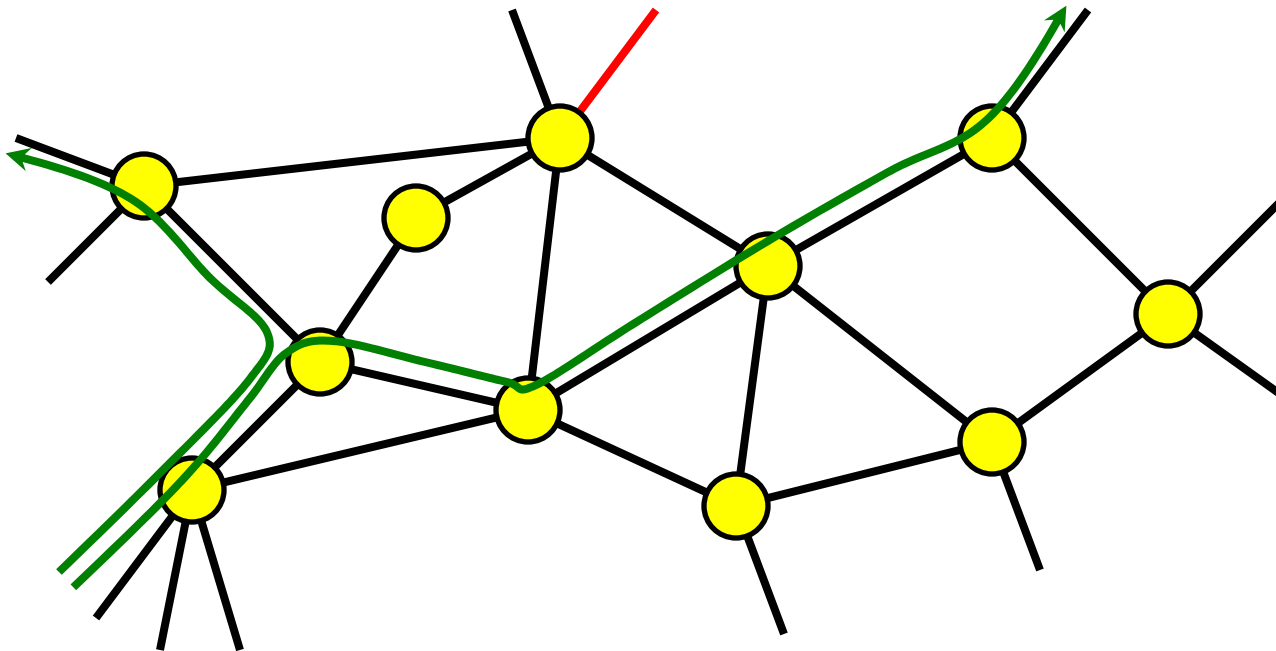
# Robustness (missing data)



Tomo-gravity

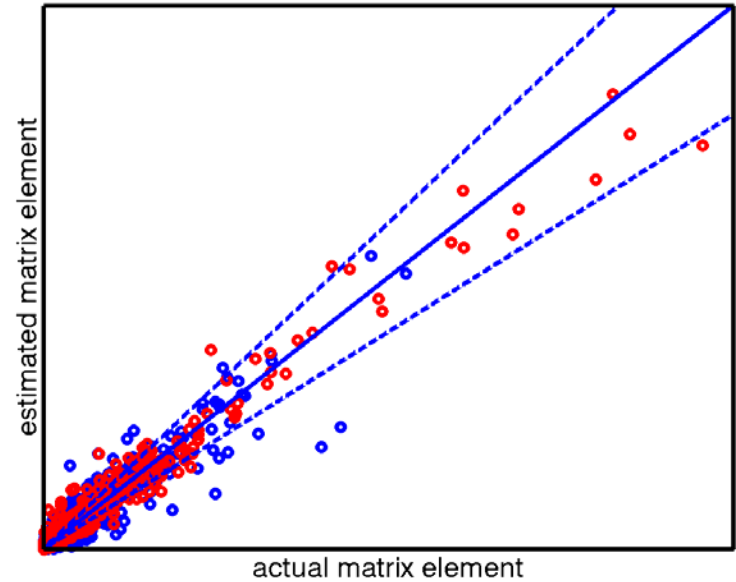
# Point-to-multipoint

We don't see whole Internet - What if an edge link fails?  
Point-to-point traffic matrix isn't invariant



# Point-to-multipoint

- ⌘ Included in this approach
- ⌘ Implicit in results above
- ⌘ Explicit results worse
  - ⊞ Ambiguity in demands in increased
  - ⊞ More demands use exactly the same sets of routes
- ⌘ use in applications is better



## Link failure analysis

